User Manual

905U Wireless I/O Module

105S Serial I/O Module

For 905U-C and 905U-D products, refer to separate User Manuals

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Thank you for your selection of the 905U / 105S module for your I/O needs. We trust it will give you many years of valuable service.

ATTENTION!

Incorrect termination of supply wires may

cause internal damage and will void warranty.

To ensure this product enjoys a long life,

double check ALL your connections with

the user's manual

before turning the power on.

Caution!

For continued protection against risk of fire, replace the module fuse F1 only with the same type and rating.

CAUTION:

To comply with FCC RF Exposure requirements in section 1.1310 of the FCC Rules, antennas used with this device must be installed to **provide a separation distance of at least 20 cm from all persons** to satisfy RF exposure compliance.

DO NOT:

- operate the transmitter when someone is within 20 cm of the antenna
- operate the transmitter unless all RF connectors are secure and any open connectors are properly terminated.
- operate the equipment near electrical blasting caps or in an explosive atmosphere

All equipment must be properly grounded for safe operations. All equipment should be serviced only by a qualified technician.

 © October 2001

FCC Notice: *905U Wireless I/O Module*

This user's manual is for the ELPRO 905U wireless I/O module. This device complies with Part 15.247 of the FCC Rules.

Operation is subject to the following two conditions:

1) This device may not cause harmful interference and

2) This device must accept any interference received, including interference that may cause undesired operation.

This device must be operated as supplied by ELPRO Technologies. Any changes or modifications made to the device without the written consent of ELPRO Technologies may void the user's authority to operate the device.

End user products that have this device embedded must be installed by experienced radio and antenna personnel, or supplied with non-standard antenna connectors, and antennas available from vendors specified by ELPRO Technologies. Please contact ELPRO Technologies for end user antenna and connector recommendations.

Notices: Safety

Exposure to RF energy is an important safety consideration. The FCC has adopted a safety standard for human exposure to radio frequency electromagnetic energy emitted by FCC regulated equipment as a result of its actions in Docket 93-62 and OET Bulletin 65 Edition 97-01.

FCC Notice: *105S Serial I/O Module*

This user's manual is for the 105S serial I/O module. This equipment has been tested and found to comply with the limit for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

-- Reorient or relocate the receiving antenna.

-- Increase the separation between the equipment and receiver.

-- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

-- Consult the dealer or an experienced radio/TV technician for help.

Important Notice

ELPRO products are designed to be used in industrial environments, by experienced industrial engineering personnel with adequate knowledge of safety design considerations.

ELPRO radio products are used on unprotected license-free radio bands with radio noise and interference. The products are designed to operate in the presence of noise and interference, however in an extreme case, radio noise and interference could cause product operation delays or operation failure. Like all industrial electronic products, ELPRO products can fail in a variety of modes due to misuse, age, or malfunction. We recommend that users and designers design systems using design techniques intended to prevent personal injury or damage during product operation, and provide failure tolerant systems to prevent personal injury or damage in the event of product failure. Designers must warn users of the equipment or systems if adequate protection against failure has not been included in the system design. Designers must include this Important Notice in operating procedures and system manuals.

These products should not be used in non-industrial applications, or life-support systems, without consulting ELPRO Technologies first.

1. For 905U modules, a radio licence is not required in many countries, provided the module is installed using the antenna and equipment configuration complying with the country's regulations.. Check with your local distributor for further information on regulations.

2. For 905U modules, operation is authorised by the radio frequency regulatory authority in your country on a non-protection basis. Although all care is taken in the design of these units, there is no responsibility taken for sources of external interference. The 905U intelligent communications protocol aims to correct communication errors due to interference and to retransmit the required output conditions regularly. However some delay in the operation of outputs may occur during periods of interference. Systems should be designed to be tolerant of these delays.

3. To avoid the risk of electrocution, the antenna, antenna cable, serial cables and all terminals of the 905U/105S module should be electrically protected. To provide maximum surge and lightning protection, the module should be connected to a suitable earth and the antenna, antenna cable, serial cables and the module should be installed as recommended in the Installation Guide.

4. To avoid accidents during maintenance or adjustment of remotely controlled equipment, all equipment should be first disconnected from the 905U/105S module during these adjustments. Equipment should carry clear markings to indicate remote or automatic operation. E.g. "This equipment is remotely controlled and may start without warning. Isolate at the switchboard before attempting adjustments."

5. The 905U/105S module is not suitable for use in explosive environments without additional protection.

Limited Warranty, Disclaimer and Limitation of Remedies

ELPRO products are warranted to be free from manufacturing defects for a period of 2 years from the effective date of purchase. The effective date of purchase is decided solely by ELPRO Technologies.

This warranty does not extend to:

- failures caused by the operation of the equipment outside the particular product's specification, or
- use of the module not in accordance with this User Manual, or
- abuse, misuse, neglect or damage by external causes, or
- repairs, alterations, or modifications undertaken other than by an authorised Service Agent.

ELPRO's liability under this warranty is limited to the replacement or repair of the product. This warranty is in lieu of and exclusive of all other warranties. This warranty does not indemnify the purchaser of products for any consequential claim for damages or loss of operations or profits and ELPRO is not liable for any consequential damages or loss of operations or profits resulting from the use of these products. ELPRO is not liable for damages, losses, costs, injury or harm incurred as a consequence of any representations, warranties or conditions made by ELPRO or its representatives or by any other party, except as expressed solely in this document.

How to Use This Manual

To receive the maximum benefit from your 905U/105S product, please read the **Introduction**, **Installation** and **Operation** chapters of this manual thoroughly before putting the product to work.

Chapter Four **Configuration** explains how to configure the modules using the Configuration Software available.

Chapter Five **Specifications** details the features of the product and lists the standards to which the product is approved.

Chapter Six **Troubleshooting** will help if your system has problems and Chapter Seven specifies the **Warranty and Service** conditions.

The foldout sheet *Installation Guide* is an installation drawing appropriate for most applications.

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Chapter One INTRODUCTION

1.1 General

The 905U & 105S range of I/O modules has been designed to provide standard "off-the-shelf" telemetry functions, for an economical price. *Telemetry* is the transmission of signals over a long distance via a medium such as radio or twisted-pair wire. Although the 905U/105S is intended to be simple in its application, it also provides many sophisticated features. This manual should be read carefully to ensure that the modules are configured and installed to give reliable performance.

The unit can monitor and control the following types of signals:

Digital on/off signals

Example outputs - motor run, siren on
Example inputs - motor fault, tank overflow, intruder alarm

Analog continuously variable signals (0-20mA)

Example outputs - tank level indication, required motor speed
Example inputs - measured tank level, actual motor speed

Pulse frequency signals

Examples - electricity metering, fluid flow

Internal Status signals

Examples - analog battery voltage, power status, solar panel status and low battery status.

The unit will monitor the input signals and transmit the signal information by radio or RS485 twisted pair to another module or modules. At the remote unit, the signals will be reproduced as digital, analog or pulse output signals. The modules also provide analog set points, so that a digital output may be configured to turn on and off depending on the value of an analog input. The pulse I/O transmits an accumulated value and the pulses are reliably recreated at the remote unit regardless of 'missed' transmissions. The actual pulse rate is also calculated and is available as a remote analog output.

This manual covers the 905U and 105S modules. We have provided a summary on all products available in the range, below.

- **905U-1, 905U-2, 905U-3 and 905U-4** modules have radio **and** serial communications. The modules differ only in their input/output (I/O) design, and are compatible, i.e. they can be used to communicate signals to each other in the same network. The 905U is a frequency hopping spread spectrum 900MHz radio.
- **105S-1, 105S-2, 105S-3 and 105S-4** modules have **only** serial communications. All other specifications are as per the 905U-1, 2, 3 & 4 modules. The 105S modules are compatible with

905U modules. 105S modules may be used for serial I/O applications, or as I/O expansion for 905U modules.

- The **905U-C** module provides an interface between host devices such as PLC's or SCADA computers, and a wireless I/O system comprising 905U modules. The 905U-C allows 905U modules to act as remote wireless I/O for the host devices. For more information, refer to the **905U-C User Manual**.

I/O Types

	905U-1	105S-1	905U-2	105S-2	905U-3	105S-3	905U-4	105S-4
Radio	✓		✓		✓		✓	
Serial	✓	✓	✓	✓	✓	✓	✓	✓
Digital Inputs (DI)	4		4				4 to 16	
Digital Outputs (DO)	4 (relay)		1 (FET)		8 (FET)		4 to 16 (FET)	
Analog Inputs (AI)	2 (4-20mA)		6 (0-20mA)					
Analog Outputs (AO)	2 (4-20mA)				8 (0-20mA)			
Pulse Inputs (PI)	1 (100Hz)		4 (1x1KHz, 3x100Hz)				4 (1x1KHz, 3x100Hz)	
Pulse Outputs (PO)	1 (100Hz)				4 (100 Hz)		4 (100 Hz)	
Comments	PI is DI 1. PO is separate to DO.		PI's are the same as DI's.		PO's are the same as DO's .		PI/ PO's are the same as DI/ DO's.	

Note regarding -4 modules. The 905U/105S-4 has a total of 20 digital I/O. Four are fixed inputs (also PI's) and four are fixed outputs (also PO's). The other 12 are selectable individually as DI or DO. The I/O range can vary from 16DI + 4DO to 4DI + 16DO or any combination in between.

All modules include power supply, microprocessor controller, input/output circuits, RS485/232 serial port, and a radio transceiver - no external electronics are required. The 905U version has both radio and serial port communications. The 105S version does not have a radio and has only serial communications. The 905U radio has been designed to meet the requirements of unlicensed operation for remote monitoring and control of equipment. That is, a radio licence is not required for the 905U modules in many countries. See Chapter Five **Specifications** for details.

Input signals connected to a module are transmitted to another module and appear as output signals. These input signals may also be configured to appear as “inverted” signals on the output. A transmission occurs whenever a "change-of-state" occurs on an input signal. A "change-of-state" of a digital or digital internal input is a change from "off" to "on" or vice-versa. A "change-of-state" for an analog input, internal analog input or pulse input rate is a change in value of the signal of 3% (configurable from 0.8 to 75 %).

In addition to change-of-state messages, update messages are automatically transmitted on a regular basis. The time period may be configured by the user for each input. This update ensures the integrity of the system.

Pulse inputs are accumulated as a pulse count and the accumulated pulse count is transmitted regularly according to the configured update time.

The I/O modules transmit the input/output data as a data frame using radio or serial RS485 as the communications medium. The data frame includes the "address" of the transmitting module and the receiving module, so that each transmitted message is acted on only by the correct receiving unit. Each transmitted message also includes error checking to ensure that no corruption of the data frame has occurred due to noise or interference. The module with the correct receiving "address" will acknowledge the message with a return transmission. If the original module does not receive a correct acknowledgement to a transmission, it will retry up to five times before setting the communications fail status of that path. In critical paths, this status can be reflected on an output on the module for alert purposes. The module will continue to try to establish communications and retry, if required, each time an update or change-of-state occurs.

A system may be a complex network or a simple pair of modules. An easy-to-use configuration procedure allows the user to specify any output destination for each input.

The maximum number of modules in one system is 95 modules communicating by radio. Each of these modules may have up to 31 other modules connected by RS485 twisted pair. Modules may communicate by radio only, by RS485 only or by both RS485 and radio. Any input signal at any module may be configured to appear at any output on any module in the entire system. Systems with a 905U-C module and host device can have more than 95 radio modules.

Modules can be used as repeaters to re-transmit messages on to the destination module. Repeaters can repeat messages on the radio channel, or from the radio channel to the serial channel (and serial to radio). Up to five repeater addresses may be configured for each input-to-output link.

The units may be configured by using a PC connected to the RS232 port. The default configuration and software configuration is defined in Section 4 **Configuration**.

Chapter Two INSTALLATION

2.1 General

The 905U/105S module is housed in a rugged aluminium case, suitable for DIN-rail mounting. Terminals are suitable for cables up to 2.5 sqmm in size.

All connections to the module should be SELV only. Normal 110/220/240V mains supply should not be connected to any input terminal of the module. Refer to Section 2.3 **Power Supply**.

Before installing a new system, it is preferable to bench test the complete system. Configuration problems are easier to recognise when the system units are adjacent. Following installation, the most common problem is poor communications on the radio channel or the serial channel. For radio modules, problems are caused by incorrectly installed antennas, or radio interference on the same channel, or the radio path being inadequate. If the radio path is a problem (i.e. path too long, or obstructions in the way), then higher performance antennas or a higher mounting point for the antenna may fix the problem. Alternately, use an intermediate module as a repeater.

For serial modules, poorly installed serial cable, or interference on the serial cable is a common problem.

The foldout sheet Installation Guide provides an installation drawing appropriate to most applications. Further information is detailed below.

Each module should be effectively earthed via a "GND" terminal on the module - this is to ensure that the surge protection circuits inside the module are effective.

2.2 Antenna Installation *(905U units only)*

The 905U module will operate reliably over large distances. The distance which may be reliably achieved will vary with each application - depending on the type and location of antennas, the degree of radio interference, and obstructions (such as hills or trees) to the radio path. Typical reliable distances are :

USA/Canada	15 miles	6dB net gain antenna configuration permitted (4W ERP)
Australia/NZ	12 km	unity gain antenna configuration (1W ERP)

Longer distances can be achieved if one antenna is mounted on top of a hill.

To achieve the maximum transmission distance, the antennas should be raised above intermediate obstructions so the radio path is true “line of sight”. Because of the curvature of the earth, the antennas will need to be elevated at least 15 feet (5 metres) above ground for paths greater than 3 miles (5 km). The modules will operate reliably with some obstruction of the radio path, although the reliable distance will be reduced. Obstructions which are close to either antenna will have more of a blocking affect than obstructions in the middle of the radio path. For example, a group of trees around the

antenna is a larger obstruction than a group of trees further away from the antenna. The 905U modules provide a test feature which displays the radio signal strength.

Line-of-sight paths are only necessary to obtain the maximum range. Obstructions will reduce the range however, but may not prevent a reliable path. A larger amount of obstruction can be tolerated for shorter distances. For very short distances, it is possible to mount the antennas inside buildings. An obstructed path requires testing to determine if the path will be reliable - refer the section 6 of this manual.

Where it is not possible to achieve reliable communications between two 905U modules, then a third 905U module may be used to receive the message and re-transmit it. This module is referred to as a repeater. This module may also have input/output (I/O) signals connected to it and form part of the I/O network - refer to Chapter 4 **Configuration** of this manual.

An antenna should be connected to the module via 50 ohm coaxial cable (eg RG58, RG213 or Cellfoil) terminated with a male SMA coaxial connector. The higher the antenna is mounted, the greater the transmission range will be, however as the length of coaxial cable increases so do cable losses. For use on unlicensed frequency channels, there are several types of antennas suitable for use. It is important antenna are chosen carefully to avoid contravening the maximum power limit on the unlicensed channel - if in doubt refer to an authorised service provider.

The net gain of an antenna/cable configuration is the gain of the antenna (in dBi) less the loss in the coaxial cable (in dB).

The maximum net gain of the antenna/cable configuration permitted is

Country	**Max. gain (dB)**
USA / Canada	6
Australia / New Zealand	0

The gains and losses of typical antennas are

Antenna	**Gain (dB)**
Dipole with integral 15’ cable	0
5dBi Collinear(3dBd)	5
8dBi Collinear (6dBd)	8
6 element Yagi	10
9 element Yagi	12
16 element Yagi	15
Cable type	**Loss (dB per 30 ft / 10 m)**
RG58	-5
RG213	-2.5
Cellfoil	-3

The net gain of the antenna/cable configuration is determined by adding the antenna gain and the cable

loss. For example, a 6 element Yagi with 70 feet (20 metres) of Cellfoil has a net gain of 4dB (10dB – 6dB).

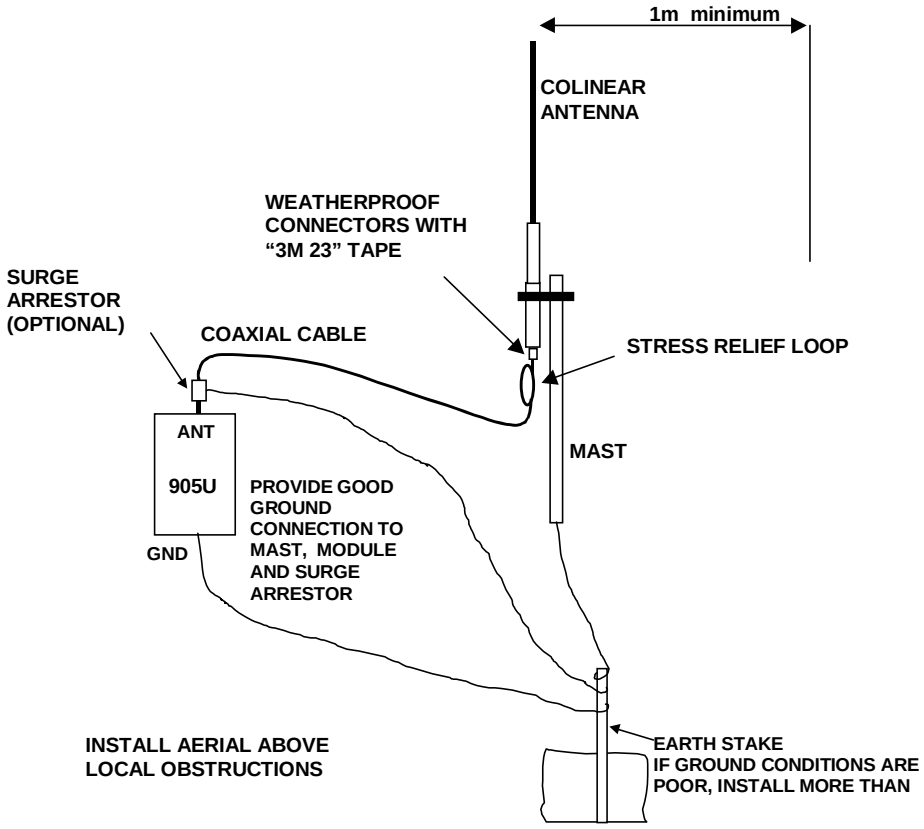
Connections between the antenna and coaxial cable should be carefully taped to prevent ingress of moisture. Moisture ingress in the coaxial cable is a common cause for problems with radio systems, as it greatly increases the radio losses. We recommend that the connection be taped, firstly with a layer of PVC Tape, then with a vulcanising tape such as "3M 23 tape", and finally with another layer of PVC UV Stabilised insulating tape. The first layer of tape allows the joint to be easily inspected when trouble shooting as the vulcanising seal can be easily removed.

Where antennas are mounted on elevated masts, the masts should be effectively earthed to avoid lightning surges. For high lightning risk areas, surge suppression devices between the module and the antenna are recommended. If the antenna is not already shielded from lightning strike by an adjacent earthed structure, a lightning rod may be installed above the antenna to provide shielding.

2.2.1 Dipole and Collinear antennas.

A collinear antenna transmits the same amount of radio power in all directions - as such that are easy to install and use. The dipole antenna with integral 15 ' cable does not require any additional coaxial cable, however a cable must be used with the collinear antennas.

Collinear and dipole antennas should be mounted vertically, preferably 1 metre away from a wall or mast to obtain maximum range.



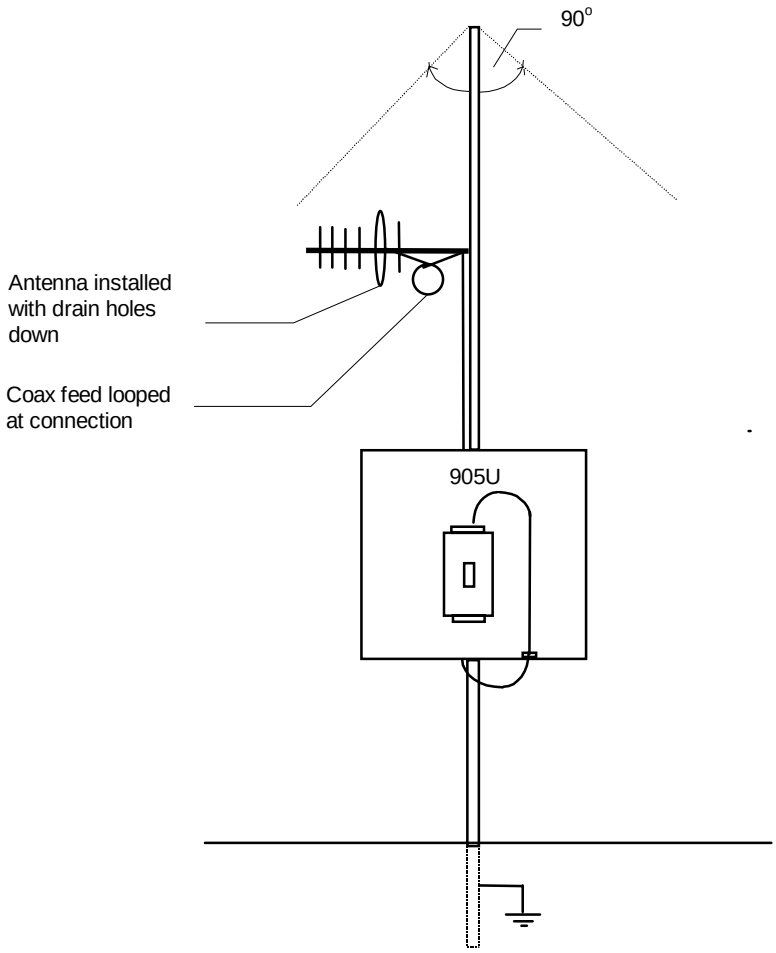
2.2.2 Yagi antennas.

A Yagi antenna provides high gain in the forward direction, but lower gain in other directions. This may be used to compensate for coaxial cable loss for installations with marginal radio path.

The Yagi gain also acts on the receiver, so adding Yagi antennas at both ends of a link provides a double improvement.

Yagi antennas are directional. That is, they have positive gain to the front of the antenna, but negative gain in other directions. Hence Yagi antennas should be installed with the central beam horizontal and must be pointed exactly in the direction of transmission to benefit from the gain of the antenna. The Yagi antennas may be installed with the elements in a vertical plane (vertically polarised) or in a horizontal plane (horizontally polarised). For a two station installation, with both modules using Yagi antennas, horizontal polarisation is recommended. If there are more than two stations transmitting to a common station, then the Yagi antennas should have vertical polarisation, and the common (or "central" station should have a collinear (non-directional) antenna.

Also note that Yagi antennas normally have a drain hole on the folded element - the drain hole should be located on the bottom of the installed antenna.



2.3 Power Supply

The 905U/105S power supply is a switch-mode design which will accept either AC or DC supply. The module may also be powered from a solar panel without an external solar regulator.

The module accepts supply voltages in the following ranges :

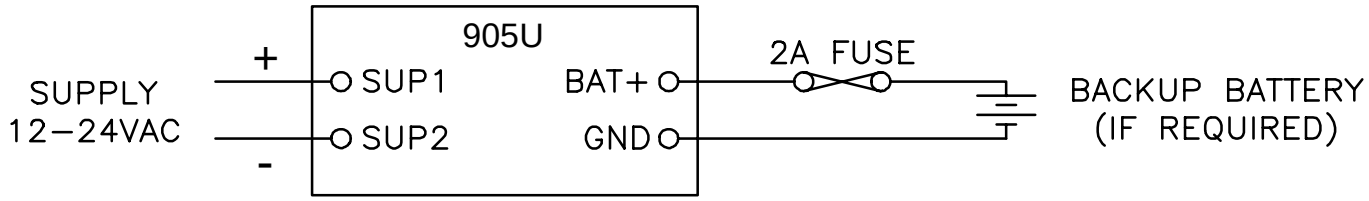
12 - 24 volts AC RMS or 15 - 30 volts DC at the “supply” terminals, or

10.8 -15 volts DC at the “battery” terminals.

The power supply should be rated at 1.5 Amps and be CSA Certified Class 2.

2.3.1 AC Supply

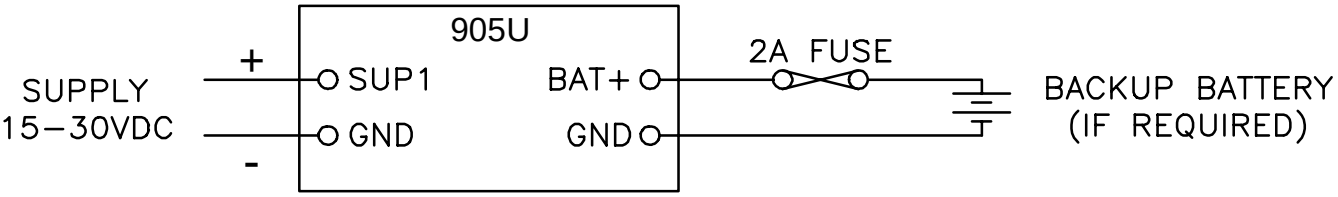
The AC supply is connected to the "SUP1" and "SUP2" terminals as shown below.



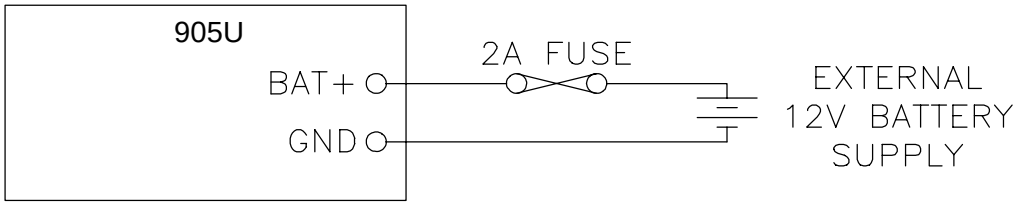
The AC supply should be "floating" relative to earth.

2.3.2 DC Supply

For DC supplies, the positive lead is connected to "SUP1" and the negative to "GND". The positive side of the supply **must not be connected to earth.** The DC supply may be a floating supply or negatively grounded.



The module may also be powered from an external 11 - 15 VDC battery supply without the need for a "normal" supply connected to "SUP1". This external battery supply is connected to "BAT+" and "GND" terminals. The positive lead of the external supply should be protected by a 2A fuse.



Upon failure of the normal supply, the module may continue to operate for several hours from a backup battery. The module includes battery charging circuits for charging up to a 12 AHr sealed lead acid battery. The battery is connected to the "BAT+" (positive) and "GND" (negative) terminals. The positive lead from the battery should be protected with a 2A fuse, installed as near to the battery terminal as possible. On return of main supply, the unit will switch back to mains operation, and recharge the battery. To provide adequate current to recharge the backup battery, an AC supply of 15V minimum or a DC supply of 17V minimum must be used. Typically, a 6 AHr battery will supply the 905U for 1 - 3 days, depending on I/O loads.

2.3.3 Solar Supply

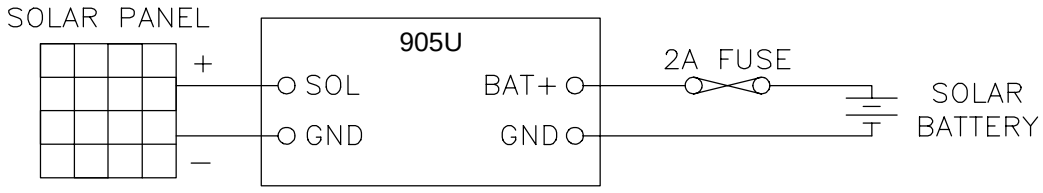
The power supply also includes a 12 V solar regulator for connecting 12V solar panels of up to 30W, and solar batteries of up to 100AHr. **The unit must not be powered from a solar panel without a battery.** A 20W solar panel is sufficient for most solar applications. The size of the solar battery required depends on the I/O used. Batteries are sized for a number of sunless days with 50% battery capacity remaining as follows:

$$\text{No. of sunless days} = \frac{\text{Battery capacity (AHr) x 0.5}}{\text{Module load (A) x 1.2 x 24}}$$

The Module load depends on the I/O connected and can be calculated as follows:

Module Load(mA) = (85 for 905U or 45 for 105S) + (10 x No. of active DI's) + (25 x No. of active DO's) + (2 x Analog loop load).

The analog loop load is the total signal current for the AI's and AO's which are powered from the internal 24V supply. Externally powered loops are not included in this.



The solar panel is connected to the "SOL" (positive) and "GND" (negative) terminals and the battery connected to the "BAT+" (positive) and "GND" (negative) terminals. Solar panels must be installed and connected as per the panel manufacturer's instructions. The positive lead of the battery should be protected by a 2A fuse installed as near as possible to the battery terminal.

Where a panel larger than 30W is required, an external solar regulator should be used.

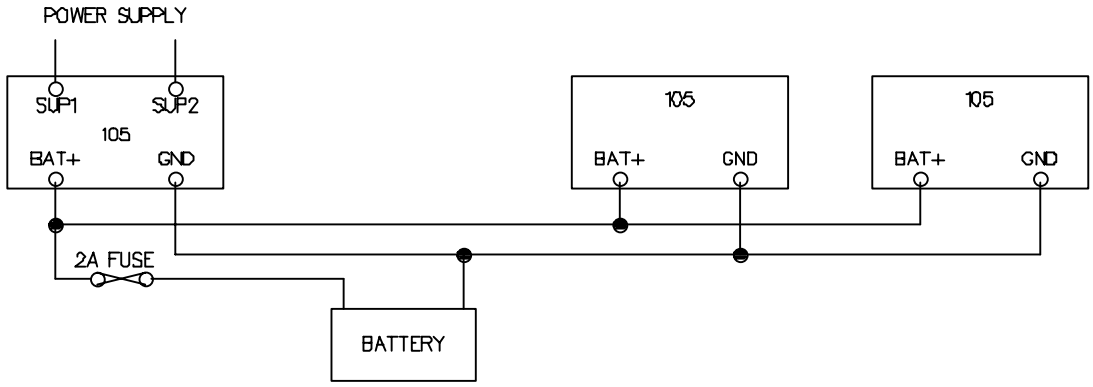
For maintenance, disconnect the solar panel first before disconnecting the battery.

2.3.4 Multiple Modules

Where more than one module is installed at the one location, a shared power supply and battery may be used, provided the total load does not exceed the power supply.

The internal power supply of the module can supply a maximum 12V load of 700mA. In order to

achieve this, the input power supply must be above 15VAC or 17VDC. Using these figures, it can be determined whether there is enough supply for more than one module - allow 100mA for recharging a battery.



For example, assume there is a 905U-1 module and a 105S-1 module at the same location. The total I/O at the location is 3 analog inputs, 6 digital inputs and 4 digital outputs. The total load will be :-

TYPE OF LOAD	LOAD mA
905U-01 quiescent	85
105S-01 quiescent	45
6 DI @ 10 mA	60
3 AI @ 20mA x 2	120
4 DO @ 25mA	100
Battery charging	100
TOTAL	510

So both modules could be powered from one power supply and one battery, provided the external supply voltage is more than 15VAC or 17VDC.

2.3.5 24V Regulated Supply

Each module provides a 24V DC regulated supply for analog loop power, except for 905U-4/105S-4. The supply is rated at 150mA, and should **only be used for analog loops**.

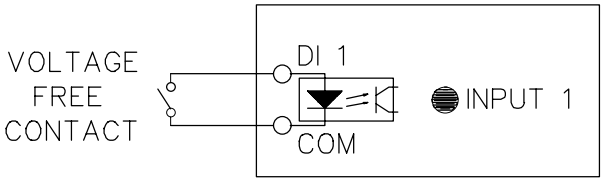
2.4 Input / Output

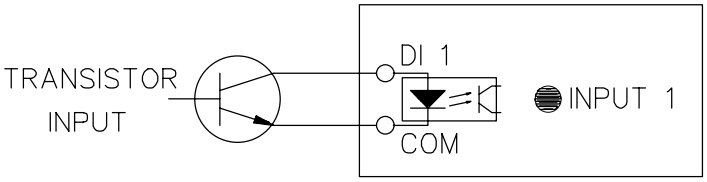
2.4.1 Digital Inputs (905-1, 905-2 and 905-4)

The ”-1” and ”-2” modules each provide four digital inputs with 5000 volt opto-isolation, and the ”-4”

provides 4 to 16 inputs with 3000 volt surge protection. All inputs are suitable for voltage free contacts (such as mechanical switches) or NPN transistor devices (such as electronic proximity switches). PNP transistor devices are not suitable. Contact wetting current of approximately 5mA is provided to maintain reliable operation of driving relays.

Each digital input is connected between the appropriate "DI" terminal and common "COM". Each digital input circuit includes a LED indicator which is lit when the digital input is active, that is, when the input circuit is closed. Provided the resistance of the switching device is less than 200 ohms, the device will be able to activate the digital input.

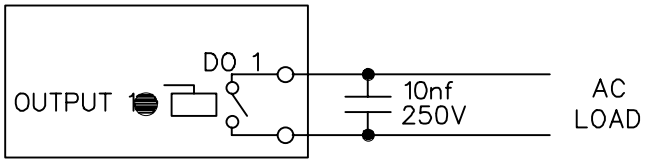


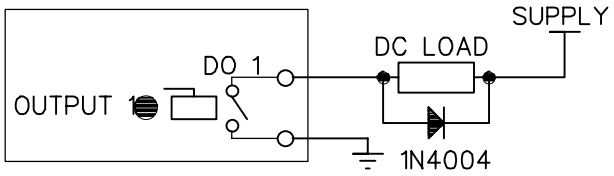


For pulse inputs, refer to Section 2.4.6.

2.4.2 Digital Outputs (905-1)

The ”-1” module provides four normally open voltage-free relay contacts, rated at AC 50V/5A, DC 30V/2A, 20V/5A. These outputs may be used to directly control low-powered equipment, or to power larger relays for higher powered equipment. When driving inductive loads such as AC relays, good installation should include capacitors (e.g. 10nf 250V) across the external circuit to prevent arcing across the relay contacts. For DC inductive loads, flyback diodes should be used to drive DC relays.





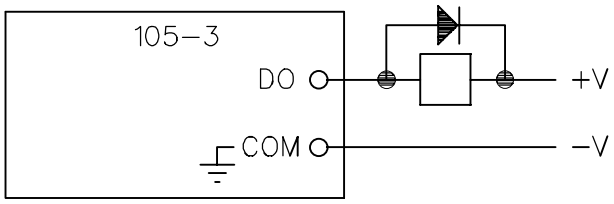
Digital outputs may be configured to individually turn off if no command message is received to that output for a certain period. This feature provides an intelligent watch dog for each output, so that a communications failure at a transmitting site causes the output to revert to a known state. See section 4.4 **Changing User Options** for further details.

The output circuit is connected to the appropriate pair of "DO" terminals. Each digital output circuit includes a LED indicator which is lit when the digital output is active.

2.4.3 Digital Outputs (905-2, 905-3 and 905-4)

The digital outputs on the “-2”, “-3” and “-4” modules are transistor switched DC signals, FET output to common rated at 30VDC 500 mA. The ”-2” provides one digital output; the ”-3” provides eight digital outputs and the ”-4” provides 4 – 16 outputs. The first four DO’s on the ”-3” and ”-4” modules are also the pulse outputs - that is, the first four DO's can be either digital outputs or pulse outputs. The function of each of these outputs may be configured individually. For a description of pulse outputs, refer to Section 2.4.7.

Digital outputs may be configured to individually turn off if no command message is received to that output for a certain period. This feature provides an intelligent watch dog for each output, so that a communications failure at a transmitting site causes the output to revert to a known state. See Chapter 4 **Configuration** for further details.

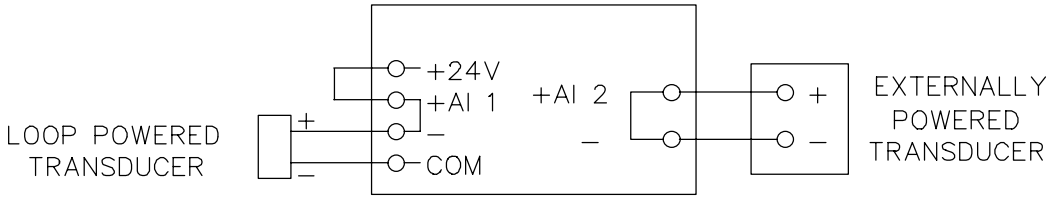


The output circuit is connected to the appropriate pair of "DO" terminals. Each digital output circuit includes a LED indicator which is lit when the digital output is active.

2.4.4 Analog Inputs (905-1 and 905-2)

The ”-1” module provides two 4 - 20 mA DC analog inputs for connecting to instrument transducers such as level, moisture, pressure transducers, etc. The ”-2” module provides six 0 - 20 mA DC analog inputs. Note that the inputs on the ”-2” module will measure down to 0mA, so they can also be used for zero based signals such as 0 - 10 mA.

Each analog input has a positive and negative terminal, and may be placed at any point in the current loop, as long as neither input rises above the 24 volt supply level. Each input has a loop resistance of less than 250 ohms and zener diode protection is provided against over-voltage and reverse voltage, however additional protection may be required in high voltage or noisy environments.



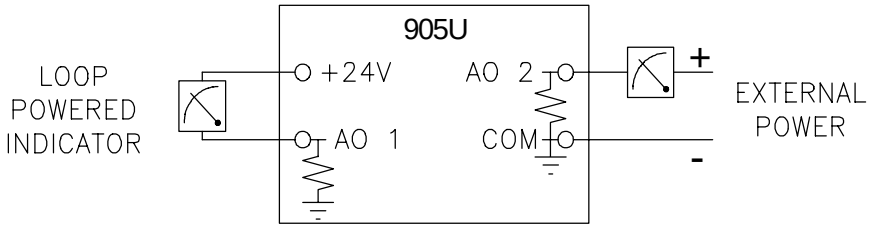
A 24VDC supply is available on the module for powering the analog transducer loops. In this case, the analog loop should be connected between a "AI 1-" terminal and "COM" (for the first analog input) or "AI 2-" (for the second analog input), and so on for other inputs. The positive terminal ("AI 1+" or "AI 2+", etc) should be connected to "+24V".

Externally powered loops may be connected by connecting the input between "AI 1+" and “AI 1-” for analog input 1 or "AI 2+" and “AI 2-” for analog input 2, and so on for other inputs. Analog Input 1 "AI 1+" may also be configured to control a high/low analog set-point. See Chapter 4 **Configuration** for further details.

Common mode voltage may be -0.5V to 27V. Shielded cable is recommended for analog I/O loops to minimise induced noise and Radio Frequency Interference (RFI). The shield of the cable should be connected to earth at one of the cable only. The use of shielded wiring inside an enclosure containing a module is also recommended.

2.4.5 Analog Outputs (905-1 and 905-3)

The ”-1” module provides two 4 - 20 mA DC analog outputs for connecting to instrument indicators for the display of remote analog measurements. The ”-3” module provides eight 0 - 20 mA DC analog outputs. Each analog output is a "sink" to common.



A 24VDC supply is available on the module for powering the analog output loop (max external loop resistance 1000 ohms). In this case, the analog loop is connected between a "+24V" terminal and "AO 1" (for the first analog output) or "AO 2" (for the second analog output), and so on for the other output signals.

Externally powered loops to 27 VDC may be connected by connecting the output between the "AO” terminal (positive) and the "COM" terminal (negative). Zener protection of analog outputs provides protection against short periods of over-voltage but longer periods **may result in module damage**. Note that the common is connected internally to ground and no other point in the analog loop should be grounded.

Analog outputs may also be configured to individually turn off (0 mA) if no command message is

received to that output for a certain period. . See Chapter 4 **Configuration** for further details.

2.4.6 Pulse Input (905-1)

For the ”-1” module, digital input 1 may be configured as a pulse input (max rate 100 Hz, min. off time 5 ms). In this mode, both the pulse **rate** and the pulse **count** are available for mapping to a remote output. The pulse rate may appear at any analog output on the remote unit, while the pulse count can appear at a Pulse Output on another ”-1” or Digital/Pulse Output on a ”-3” or “-4” unit. The pulse input should be connected in the same way as a digital input.

2.4.7 Pulse Inputs (905-2 and 905-4)

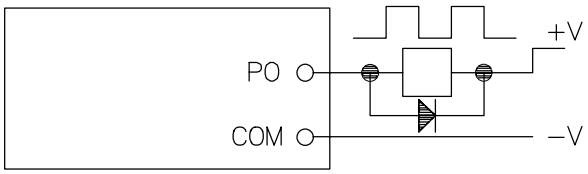
For the ”-2” and ”-4” modules, the four digital inputs (DI 1-4) may be configured as pulse inputs. The first digital/pulse input DI 1 has a maximum rate of 1000 Hz (min. off time 0.5 ms), while DI 2-4 have a maximum rate of 100 Hz (min. off time 5 ms). When using DI 1 at high pulse rates (more than 100 Hz), a divide by 10 function may be configured to reduce the pulse count at the output, as Pulse Outputs have a maximum rate of 100 Hz.

For each pulse input, both the pulse **rate** and the pulse **count** are available for mapping to a remote output. The pulse rate may appear at any analog output on the remote unit, while the pulse count can appear at a Pulse Output. The default update time for pulse counts is 1 minute. This can be changed by changing the update time configuration - refer Chapter 4 **Configuration** for further details. The pulse count is a 16 bit value - “roll over” of the count when it exceeds the maximum value is automatically handled by the modules.

Pulse inputs should be wired in the same way as digital inputs (see Section 2.4.1).

2.4.8 Pulse Output (905-1)

A single FET output to common rated at 30VDC, 500 mA is provide for the pulse output "PO". This output accurately recreates the pulses counted at a pulse input at another module.



Although the count is accurately re-created, the rate of output pulses may not accurately reflect the input rate. The actual input pulse rate may be configured to appear at an analog output if required. Note that the pulse rate and accumulated value will remain accurate even if a period of communications failure has occurred. The maximum output rate is 100 Hz.

2.4.9 Pulse Output (905-3 and 905-4)

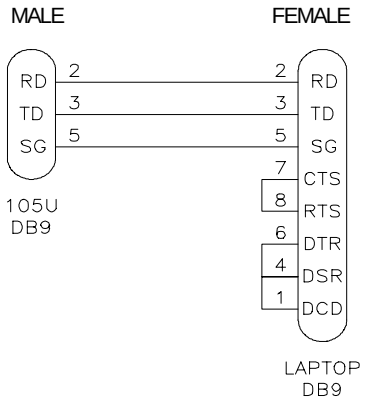
The first four digital outputs on the ”-3” and ”-4” modules may also be used as pulse outputs. The outputs are FET output to common rated at 30VDC, 500 mA. The outputs will provide a pulse signal

of up to 100 Hz. The outputs accurately recreate the pulses counted at pulse inputs at a ”-1”, ”-2” or “-4” module.

Although the count is accurately re-created, the rate of output pulses may not accurately reflect the input rate. The actual input pulse rate may be configured to appear at an analog output if required. Note that the pulse rate and accumulated value will remain accurate even if a period of communications failure has occurred.

2.4.10 RS232 Serial Port

The serial port is a 9 pin DB9 female and provides for connection to a terminal or to a PC for configuration, field testing and for factory testing. This port is internally shared with the RS485 - ensure that the RS485 is disconnected before attempting to use the RS232 port. Communication is via standard RS-232 signals. The 905U/105S is configured as DCE equipment with the pin-out detailed below. The serial port communicates at a baud rate of 9600 baud, 8 bits, no parity, one stop bit. An example cable drawing for connection to a laptop is detailed below:



Pin	Name	Dirn	Function
1	DCD	Out	Data carrier detect - not used
2	RD	Out	Transmit Data - Serial Data Input (High = 0, Low = 1)
3	TD	In	Receive Data - Serial Data Output (High = 0, Low = 1)
4	DTR	In	Data Terminal Ready - not used
5	SG	-	Signal Ground
6	DSR	Out	Data Set Ready - not used
7	RTS	In	Request to Send - not used
8	CTS	Out	Clear to send - not used
9	RI	-	Ring indicator - not used.

2.4.11 RS485 Serial Port

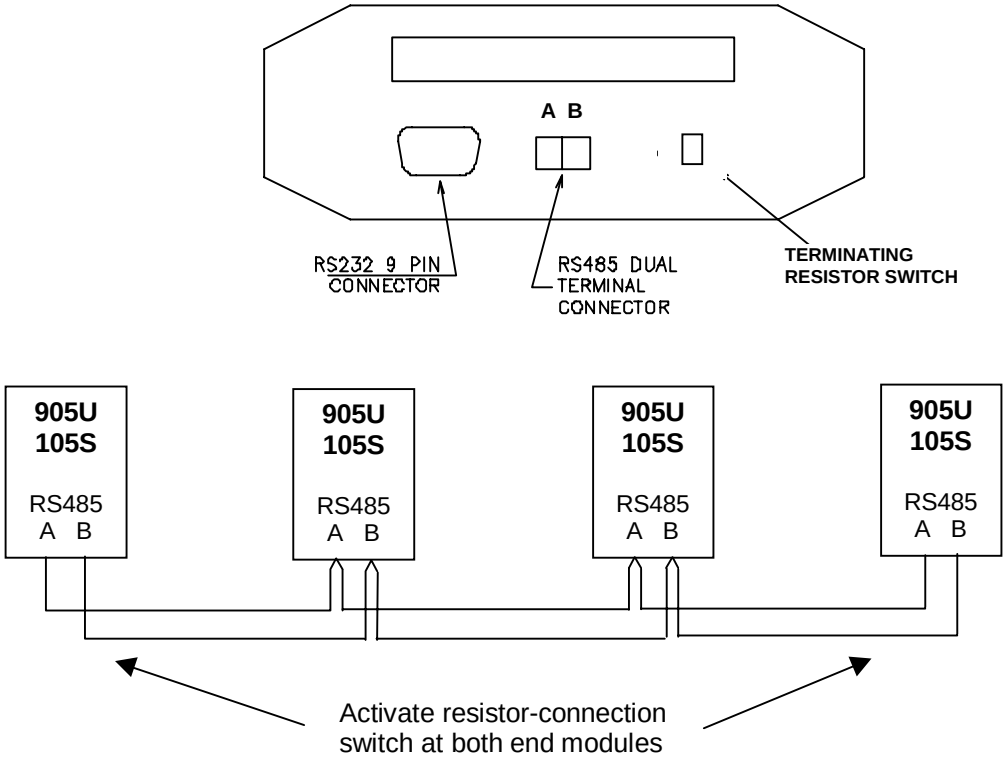
The RS485 port provides for communication between multiple units using a multi-drop cable. Up to 32 units may be connected in each multi-drop network. Each multi-drop network may have one unit providing radio communications with other units in the system. The RS485 feature allows local hubs of control to operate without occupying radio bandwidth required for communication between remotely sited units.

The RS485 Communications format is 9600 baud, 8 data bits, one stop bit, no parity. Note that the RS485 port is shared internally with the RS232 port - disconnect the RS232 cable after configuration is complete.

RS485 is a balanced, differential standard but it is recommended that shielded, twisted pair cable be

used to interconnect modules to reduce potential Radio Frequency Interference (RFI). An RS485 network should be wired as indicated in the diagram below and terminated at each end of the network with a 120 ohm resistor.

The 905U modules include a terminating resistor on-board. If the 905U module is the first or last module in the RS485 chain, then the terminating resistor may be connected by operating the single DIP switch in the end-plate next to the RS485 terminals. "On" or "down" means that the resistor is connected. The 105S does not have the terminating resistor built onto the board and must be added externally.



Chapter Three OPERATION

3.1 Power-up and Normal Operation

When power is initially connected to the module, the module will perform internal diagnostics to check its functions. The following table details the status of the indicating LED's on the front panel under **normal** operating conditions.

LED Indicator	Condition	Meaning
OK	On	Normal Operation
RX	Occasional flash	Radio Receiving, or Activity on serial ports
RX	Flashes continuously	Configuration Mode
RX	On	Button press when entering Configuration Mode
TX (only on 905U units)	Occasional flash	Radio Transmitting
PWR	On	Supply voltage available from Solar Panel or SUP1/SUP2
OK	Flashes every 5 seconds	+24V Supply overloaded

Additional LED's provide indication of the status of digital inputs and outputs. LED's display the status of each digital input (lit for active), and LED's display the status of each digital output (lit for active). Other conditions indicating a fault are described in Chapter Six **Troubleshooting**.

The module monitors the power supply and provides status of supply failure and battery low voltage for "mapping" to one of the module's own outputs or transmitting to a remote output. When the module is powered from a normal supply (i.e. via either of the "SUP" terminals), the *PWR* LED indicator is lit. When the modules is powered from a solar panel and battery, the *PWR* LED indicator is lit only when the charge current is available (i.e. when the solar panel is receiving light).

If a backup battery is connected, the module will generate a low battery voltage status when the voltage has dropped to 11.3V for approx 45 seconds. This status may be transmitted to another module. In the event of excessively low battery voltage (10.8V), the *OK* LED will go off, the unit will automatically set all outputs off, and disable the +24V analog loop supply. the *OK* LED will turn on again after the battery voltage exceeds 11.8V. This enables installations to be configured so that the battery current drain is minimised in the event of extended mains failure, reducing the possibility of deep discharge of batteries.

3.1.1 Communications

If transmissions are not successful (radio or serial), then the module will re-try up to four times at random intervals to transmit the message.

Example of Successful Communications

Local Unit		Remote Unit
• Listen to ensure channel is clear		
• If clear, transmit message TX LED flashes if radio RX LED flashes if RS485	→	• Receive message RX LED flashes Check message for integrity
• RX LED flashes • Acknowledgement received okay – communication complete	←	• If message okay, transmit it back as acknowledgement TX LED flashes if radio RX LED flashes if RS485 Outputs updated as per message received.

Example of unsuccessful communications

Local Unit		Remote Unit
• Listen to ensure channel is clear		
• If clear, transmit message TX LED flashes if radio RX LED flashes if RS485	→	• Receive message RX LED flashes Check message for integrity Message corrupted - do nothing
• No acknowledgement received • Retry up to four times • Still no acknowledgement "Comms fail" status to remote unit set If status is mapped to an output, set output	(4) →	• If no update received for an output within watchdog timeout, check to see if the output is configured to reset • Reset outputs if configured

If communications is still not successful, the "Comms Fail" internal status will be set. In the default configuration, this will have no consequence and the module will continue to attempt to transmit to the remote module every ten minutes. For critical applications, the "comms fail" status can be configured to be reflected to an output on the module for alert purposes. The outputs on the module may also be configured to reset after a specified timeout (digital outputs reset to "off", analog outputs reset to 0 mA) allowing the system to turn off in a controlled manner e.g. a pump will never be left running because of a system failure.

Repeaters can be used in a system to increase range. Each 905U unit can be configured to act as a repeater. When configuring an input to be mapped to an output, the communications path to the output unit, including the repeater addresses is specified. The 905U acts as a *store&forward repeater*, that is, the signal is decoded and then retransmitted "as new".

Example Repeater Communications

Unit A DI 1 mapped to Unit D DO1 via Units B & C

Unit A	Unit B Repeater	Unit C Repeater	Unit D
• DI 1 is turned on			
• Transmit →	• Receive		
• Receive ←	• Transmit on with Acknowledge →	• Receive	
	• Receive Acknowledge ←	• Transmit on with Acknowledge →	• Receive
		• Receive Acknowledge ←	• Transmit acknowledge
			• DO 1 is turned on

3.1.2 Change of state conditions

The module transmits a data message whenever it detects a "change-of-state" on one of its input signals. A "change-of-state" of a digital or digital internal input is a change from "off" to "on" or vice-versa provided the change is sustained for 0.5 second (i.e. 0.5 second debounce). The debounce delay is configurable.

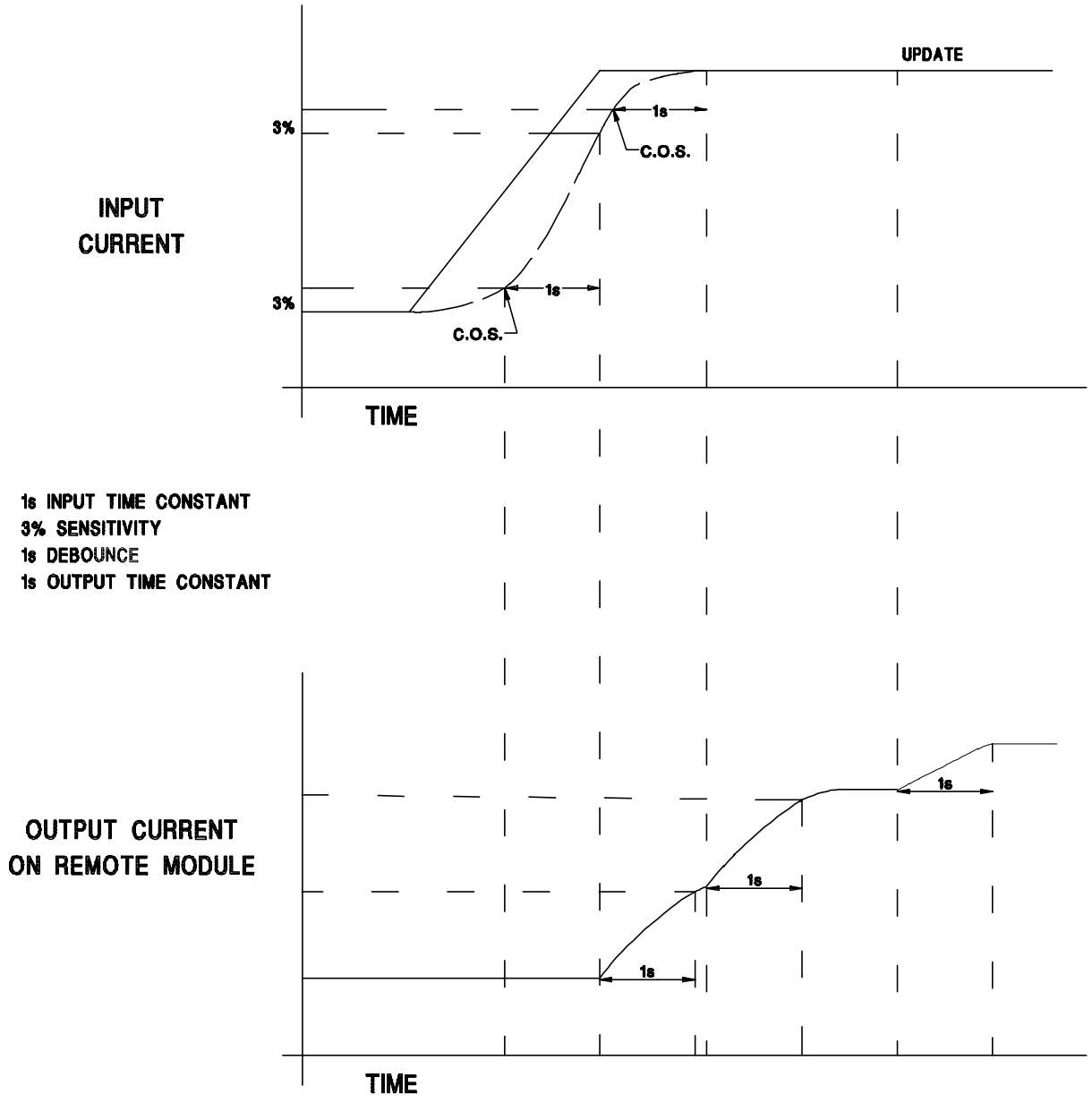
In addition to "change-of-state" transmissions, each module will transmit the status of each input to its corresponding output every ten minutes (configurable). These **updates** mean that the outputs are set to the current input values regularly, even where no "change-of-state" has occurred. These update transmissions increase the accuracy of the output and give extra system reliability.

Analog Change-of-state

A "change-of-state" for an analog input, battery voltage or pulse input rate is a change in value of the signal of 3% (configurable) since the last transmission. Note that the sensitivity of 3% refers to 3% of the analog range, not 3% of the instantaneous analog value. That is, if an analog input changes from 64% (14.24 mA) to 67% (14.72 mA), a "change-of-state" will be detected. This “change-of-state” sensitivity is configurable between 0.8% and 75%.

Analog inputs are digitally filtered to prevent multiple transmissions on continually varying or "noisy" signals. The input is filtered with a 1 second time constant and a 1 second debounce. The analog outputs are filtered with a 1 second time constant.

An **example** of an **analog** input and how the output follows it is shown below:



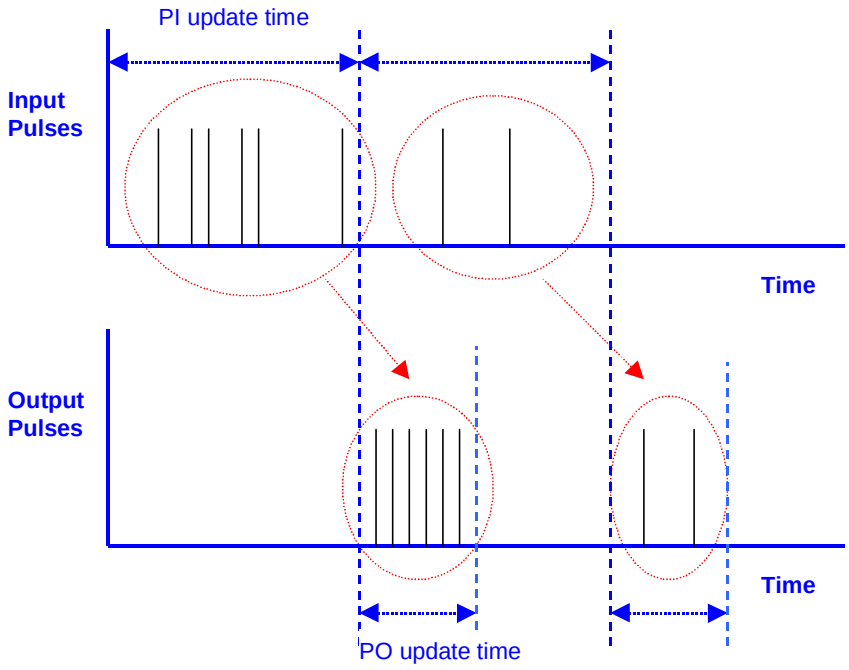
In general, the following may be used as a rule of thumb for calculating the appropriate sensitivity required for a given application:
Instantaneous change of 2 x sensitivity on input → 3 second output response
Instantaneous change of 10 x sensitivity on input → 5 second output response

The analog inputs have 15 bit resolution and 0.016mA accuracy.

Pulse input change of state

Pulse input counts do not use "change-of-state" transmissions. Instead, accumulated pulse input counts are transmitted at set intervals. The default period is 1 minute and is configurable. The absolute pulse count is transmitted. If the PI is transmitted to a PO on a 905U/105S module, then the pulse outputs are re-created from the *accumulated* pulse count. Rollovers of the pulse count thru zero are catered for. If a transmission is missed, the pulse output will still be re-created when the next accumulated value is transmitted. This ensures that no pulses are lost due to communications failures. If the PI is transmitted to a 905U-C interface module, then the accumulated pulse count is stored in the 905U-C for interfacing to the host device.

The following diagram shows how pulse inputs are re-created as pulse outputs. For pulse outputs, the module keeps two counters in memory - the pulse input count received from the remote module, and the count of output pulses. When the receives an update of the input pulse count, it will output pulses until the output pulse count is the same as the input pulse count. The output pulse will be output evenly over the pulse output update time which is configured in the module. For example, assume that module receives a pulse input update message from the remote module, and the difference between the pulse input count and the pulse output count is 12 pulses. The module will then output the 12 pulses evenly over the next minute (if the pulse output update time is 1 minute).



The default values for the pulse input update time and pulse output update time is 1 minute. In this

case, the output pulses are effectively 1 minute behind the input pulses. These update times may be changed by the user. The pulse output update time should not be set to be more than the pulse input update time. Note that the maximum pulse rate for both inputs and outputs is 100Hz.

As well as accumulating the pulse input, the module will also calculate the rate of pulses. **Pulse rates** are treated as an "internal" analog input and are configured with analog sensitivities for change-of-state transmissions. The maximum pulse rate corresponding to 20mA output may be configured by the user.

3.1.3 Analog Set-points

On "-1" modules, the "AI 1" input may be used to trigger the analog set-point status. High set point and low set point levels are configurable. This set-point status turns ON when the analog input moves below the low level, and turns OFF when it moves above the high level. The high level must always be greater than, or equal to, the low level set point. This set-point status may be mapped (inverted, if required) to any output in the network. The set-point status is effectively an internal digital input.

On "-2" modules, each analog input has set-point values for controlling digital outputs. The set-point operation works as for the "-1" module.

3.1.4 Start-up Poll

After a module has completed its initial diagnostics following power up, it will transmit update messages to remote modules based on the values of the module's inputs. The module's outputs will remain in the reset/off/zero condition until it receives update or "change-of-state" messages from the remote modules.

The module can transmit a special "start-up poll" message to another module. The remote module will then immediately send update messages to this module such that its outputs can be set to the correct value. Start-up polls will only occur if they are configured. It is necessary to configure a start-up poll to each remote module which controls the module's outputs. For further information, refer to Chapter 4 **Configuration**.

3.1.5 Communications Failure (CF)

The internal communications failure (CF) status is set if a module does not receive an acknowledgement message after five attempts at transmitting a message. The CF status may be configured to set a local digital output for an external alarm.

Although the CF status can set an output, it will not reset the output. That is, once communications is re-established (and the CF status is reset), the output will stay "on". The Reset Output feature (see below) is used to reset the output.

The output will reset only when no communications failures occur within the configured "Reset Output Time" for the output that CF status is mapped to. Note that if the reset output time is not enabled, the CF status will remain set forever, once an unsuccessful transmission occurs. See Chapter 4 **Configuration** for further details.

For a link with one or more repeaters, the internal CF status will only set for a failure between the transmitting module (the source module) and the first repeater. If the communications failure occurs

after the first repeater, then the source module CF status will not set. To indicate comms status on this type of link, the "Reset Output" function should be used.

3.1.6 Resetting Outputs

Each digital and analog output may be individually configured to reset if that output has not received a change-of-state or an update message within a certain time period. Generally this time is set to twice the update period, so at least one update can be missed before an output is reset.

In most cases it is desirable to reset outputs which are controlling equipment if there is a system failure, however alarm or indication outputs are not reset so the last valid indication remains shown. See Chapter 4 **Configuration** for further details.

3.2 System Design Tips

The following tips will help to ensure that your system operates reliably.

3.2.1 System Dynamics

It is important to be aware of the dynamics of the system. Digital inputs have a minimum "debounce" delay of 0.5 sec - that is, a change message will not be sent for 0.5 sec after a change has occurred. Analog inputs and outputs have time delays of 1 to 2 seconds.

Messages transmitted via serial link are received in less than 20 mSec, however a message sent by radio takes approx 60 mSec.

These delays are not significant is most applications, however if your application requires faster responses, then the above delays need to be considered.

3.2.2 Radio Channel Capacity

Messages sent on a cable link are much faster than on a radio channel, and the capacity of the radio channel must be considered when designing a system. This becomes more important as the I/O size of a system increases.

The modules are designed to provide "real-time" operation. When an input signal changes, a change message is sent to change the output. The system does not require continuous messages to provide fast operation (as in a polling system). Update messages are intended to check the integrity of the system, not to provide fast operation. Update times should be selected based on this principle. The default update time is 10 minutes - we recommend that you leave these times as 10 minutes unless particular inputs are very important and deserve a smaller update time.

It is important that radio paths be reliable. For large systems, we recommend a maximum radio channel density of 100 messages per minute, including change messages and update messages. We suggest that you do not design for an average transmission rate of greater than 40 per minute - this will give a peak rate of approx 100 per minute. Note that this peak rate assumes that all radio paths are

reliable - poor radio paths will require re-try transmissions and will reduce the peak channel density. If there are other users on the radio channel, then this peak figure will also decrease.

3.2.3 Radio Path Reliability

Radio paths over short distances can operate reliably with a large amount of obstruction in the path. As the path distance increases, the amount of obstruction which can be tolerated decreases. At the maximum reliable distance, "line-of-sight" is required for reliable operation. If the path is over several kilometres (or miles), then the curvature of the earth is also an obstacle and must be allowed for. For example, the earth curvature over 5 miles (8km) is approx 10 feet (3m), requiring antennas to be elevated at least 13 feet (4m) to achieve "line-of-sight" even if the path is flat.

A radio path may act reliably in good weather, but poorly in bad weather - this is called a "marginal" radio path. If the radio path is more than 20% of the maximum reliable distance (see Specification section for these distances), we recommend that you test the radio path before installation. Each 905U module has a radio path testing feature - refer to section 6.2 of this manual.

There are several ways of improving a marginal path :-

- Relocate the antenna to a better position. If there is an obvious obstruction causing the problem, then locating the antenna to the side or higher will improve the path. If the radio path has a large distance, then increasing the height of the antenna will improve the path.
- Use an antenna with a higher gain. Before you do this, make sure that the radiated power from the new antenna is still within the regulations of your country. If you have a long length of coaxial cable, you can use a higher gain antenna to cancel the losses in the coaxial cable.
- If it is not practical to improve a marginal path, then the last method is to use another module as a repeater. A repeater does not have to be between the two modules (although often it is). If possible, use an existing module in the system which has good radio path to both modules. The repeater module can be to the side of the two modules, or even behind one of the modules, if the repeater module is installed at a high location (for example, a tower or mast). Repeater modules can have their own I/O and act as a "normal" 905U module in the system.

3.2.4 Design for Failures

All well designed systems consider system failure. I/O systems operating on a wire link will fail eventually, and a radio system is the same. Failures could be short-term (interference on the radio channel or power supply failure) or long-term (equipment failure).

The modules provide the following features for system failure :-

- Outputs can reset if they do not receive a message within a configured time. If an output should receive an update or change message every 10 minutes, and it has not received a message within this time, then some form of failure is likely. If the output is controlling some machinery, then it is good design to switch off this equipment until communications has been re-established.

  The modules provide a "drop outputs on comms fail" time. This is a configurable time value for

each output. If a message has not been received for this output within this time, then the output will reset (off, in-active, "0"). We suggest that this reset time be a little more than twice the update time of the input. It is possible to miss one update message because of short-term radio interference, however if two successive update messages are missed, then long term failure is likely and the output should be reset. For example, if the input update time is 3 minutes, set the output reset time to 7 minutes.

- A module can provide an output which activates on communication failure to another module. This can be used to provide an external alarm that there is a system fault.

3.2.5 Indicating a Communications Problem

There are two ways to provide an indication of communications problems. The first is to map the internal CF status to a local output. The output will then activate when a comms fail occurs. This method provides an indication immediately an attempt to transmit a message fails. If you want the radio path to be "tested" regularly, then you need to configure the update times such that transmissions occur regularly (however do not overload the radio channel).

Notes regarding this method:

1. Each CF mapping corresponds to only one remote address - you need to make separate mappings for each remote address. You can map the CF for each remote module to a separate output, or to the same output.

2. You need to reset the comms fail output using the "reset output" parameter. Select a reset time which is greater than the effective update time period. For example, if there are four inputs mapped from module #1 to module #2, each with a 10 minute update, then you would expect at least four transmissions in each 10 minute period. At module #1, a comms fail for #2 is mapped to DO1. If you set the "reset time" for DO1 to 10 minutes, then there will be at least four transmissions made during the reset period - that is, the output will only reset when the communications has been successful four times.

3. This method will not work for radio links with repeaters. If a repeater is used, you will need to use the second method described below.

The second method is to set up a "comms OK" output using the "Reset Outputs" function. Consider a link between module #1 and #2, and assume that you want a "comms OK" output at #1. At #2, map an unused input to an output at #1 such that the output is normally active ('on"). If there is no spare inputs at #2, you can use an internal input such as "low voltage status". You will need to invert the mappings such that the output is normally on (because the input is normally off).

At #1, configure a reset time for the output. The reset time should be greater than the update time for the mapping at #2. If #1 fails to receive update messages from #2, then the output will reset, indicating a communications failure. Notes regarding this method:

1. This method will work with repeaters in the link.

2. The "comms OK" output is fail-safe - if module #1 fails, then the output will reset indicating a

problem.

3. You should use separate outputs to indicate “comms OK” of different remote modules.

4. It is recommended that you set the reset time at #1 to more than twice the update time of the mapping at #2. This means that the comms OK output will only reset if #1 misses two consecutive updates from #2.

3.2.6 Testing and Commissioning

We recommend that you set-up and test the system with all of the modules together **before** you install the modules. It is much easier to find a configuration problem.

When the system is configured, record the radio signal strength and background noise level for each radio link. If there are future communications problems, you can compare the present measurements to the as-commissioned values. This is an effective way of finding problems with antennas, cables and also changes in the radio path (for example, the erection of new buildings).

Chapter Four CONFIGURATION

4.1 Introduction

The modules are configured by connecting a computer (PC) using the Configuration Software program. The same software program is used to configure 905U-C modules - for more information, refer to the separate 905U-C User Manual. Each module is configured with a system address and a unit address. The system address is common to every module in the same system, and is used to prevent "cross-talk" between modules in different systems. Separate networks with different system addresses may operate independently in the same area without affecting each other. The system address may be any number between 1 and 32 767. The actual value of the system address is not important, provided all modules in the same system have the same system address value. **A system address of zero should not be used.** The use of a random number is recommended.

Each unit must have a unique unit address within the one system. A valid unit address is 1 to 127. A network may have up to 95 addresses communicating via radio (unit addresses 1 to 95), each with up to 31 modules communicating via RS485 (unit addresses 96 to 127). In the network, any individual input signal may be "mapped" to one or more outputs anywhere in the system. The unit address determines the method of communication to a module. Any module with a unit address between 96 and 127 will communicate by RS485 only. Other units with a unit address below 95 may communicate by radio *or* RS485 - the unit will determine which way to communicate depending upon the unit address of the destination module. For example, Unit 31 will talk to Unit 97 by RS485 only, but will talk to unit 59 by radio only. 105S units must always have a unit address between 96 and 127 as serial communication is the only method of communication available. **A unit address of zero should not be used.**

The four different I/O versions in the range can be used together in the same system. 905U-C modules can also be part of a system. Inputs to one product type can be transmitted to outputs of another product type. For example, an analog input to a ”-2” may be transmitted to an analog output of a ”-1” or ”-3”. Repeaters may be any product type.

The ”-1” and ”-2” modules require only one unit address. The ”-3” and ”-4” modules use two addresses, however only one unit address has to be entered. The ”-3” and ”-4” modules require two addresses because of the large number of output channels. If the “entered" unit address is an even number, then the second address is the next number. If the "entered" address is an odd number, then the second address is the previous number. So the two addresses are two subsequent numbers, starting with an even number. If a ”-3” module is given a unit address of 10, then it will also take up the unit address 11 and will accept messages addressed to either 10 or 11. It is important to remember this when allocating unit addresses to other modules in the system.

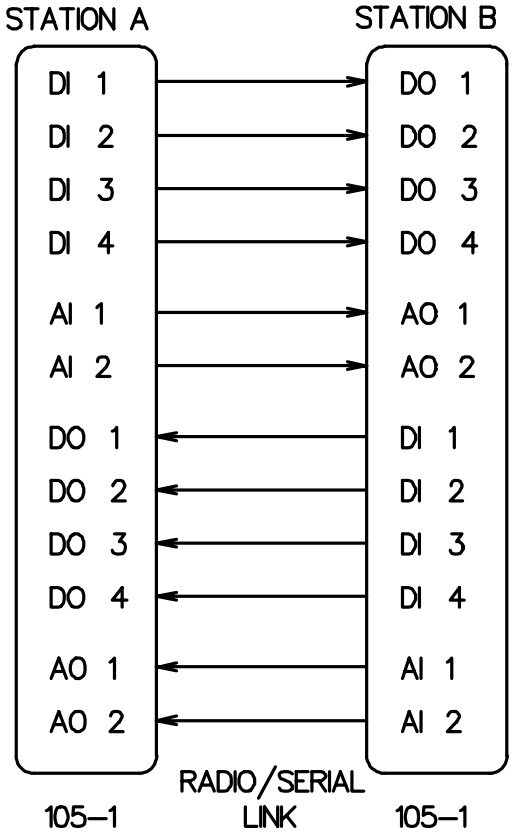
Warning - do not allocate the address number 1 to a “-3” or “-4” module.

In addition to these network configurations, operational parameters called **User Options** may be configured to change the features of the operation.

4.2 Easy Configuration Using Default Settings

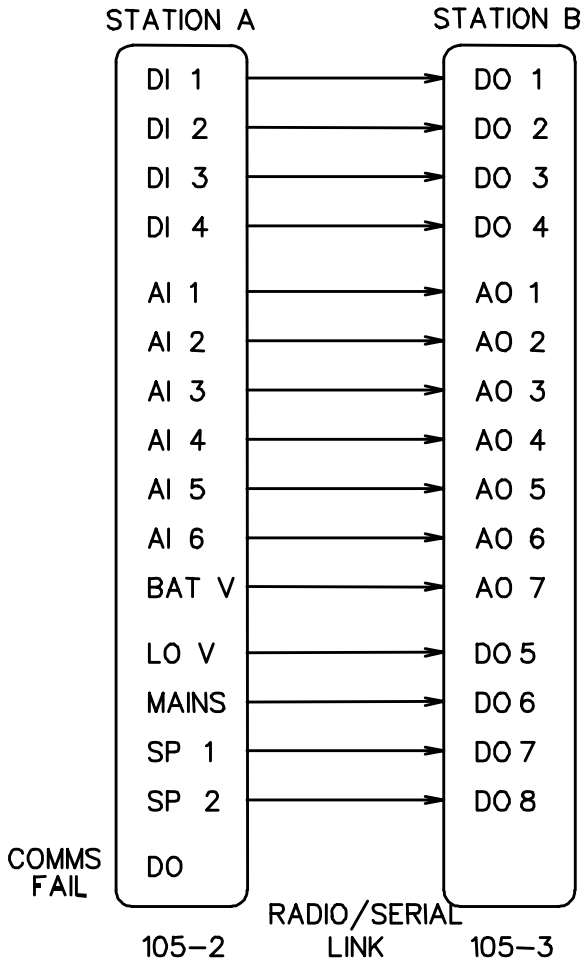
If your application requires only a single pair of modules, communicating via radio or serial link, default settings may satisfy your needs. If so, no configuration is required. Essentially, all inputs at Module A are reflected at the corresponding outputs at Module B. All inputs at Module B are reflected at the corresponding outputs at Module A.

For "-1" modules, the default configuration is as follows :-



In this configuration, the "PO" Pulse output is inactive and no special action is taken on "Comms fail", "Mains fail" or "Battery Low". "DI 1" is configured as a digital and not a pulse input.

For "-2" and "-3" modules, the default configuration is as follows :-



Note that there is no default configuration for the "-4" modules.

The following table details the default values for **User Options**:

Option	Factory Set Value
Update transmissions	Every 10 minutes
Analog Change-of-state sensitivity	3%
Reset outputs on Comms fail	No
Analog Setpoints (if mapped)	Low Set point = 30% High Set point = 75%
Pulse Output Rate Scaling (if Pulse Rate is mapped)	100 Hz
Digital Input Debounce Time	0.5 seconds

If any of the above values are not appropriate to your system, Section 4.4 below will detail how to change one or all of the above variables.

4.3 Configuration Software

This chapter describes installation and operation of configuration software for the radio and serial telemetry modules.

The configuration software runs on a conventional PC as a Windows application. The software creates a configuration file which can be loaded into a module via RS232. The configuration software also allows the configuration of a module to be loaded for display and modification. Configuration files are created and stored in project directories.

Configuration of modules consists of entering I/O mappings, and selecting User Options. An I/O mapping is a link between an input on the module being configured and an output on another module. A mapping has the form :-

DI3 → Out2 at 4 via 3, 11

This mapping links DI3 on this module to output channel 2 on the module with address 4, and modules 3 and 11 are repeaters.

User Options may be selected to change the configuration of specific features.

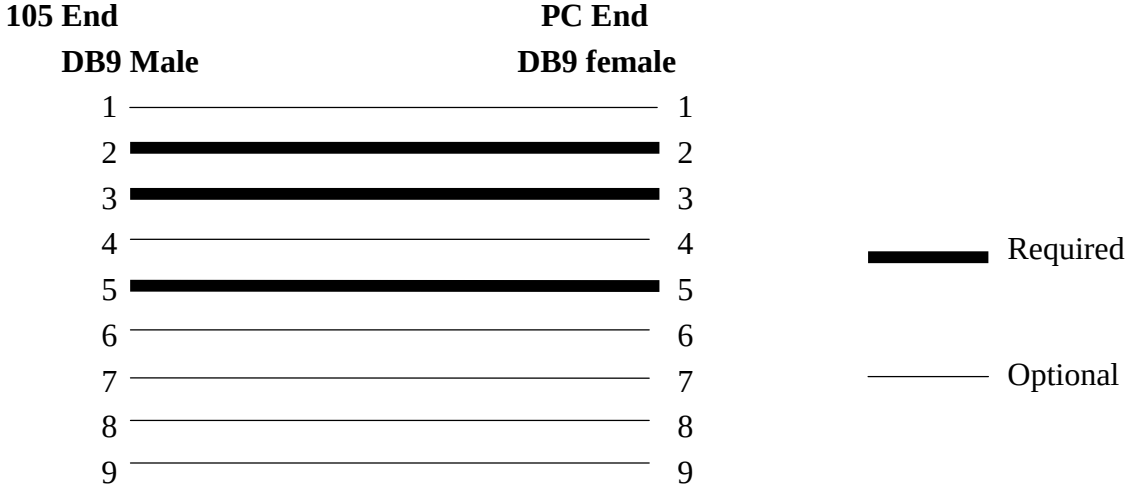
Mappings configured to a 905U-C have the form :-

AI2 → I/O Reg 1036 at 10 via 7

This mapping links AI2 on a 905U module to I/O Register 1036 in a 905U-C with address 10. Module #7 is used as a repeater. The host device connected to the 905U-C can read the I/O register.

4.3.1 Hardware and Software Requirements

The configuration software is available on a CD, and needs to be installed on your PC before you can use it. The CD contains a setup file called *setup.exe*. Select the configuration software window on the Product CD and an installation Wizard will guide you through the installation procedure. To upload and download configuration files to a module, you will need a RS-232 serial cable as shown below.

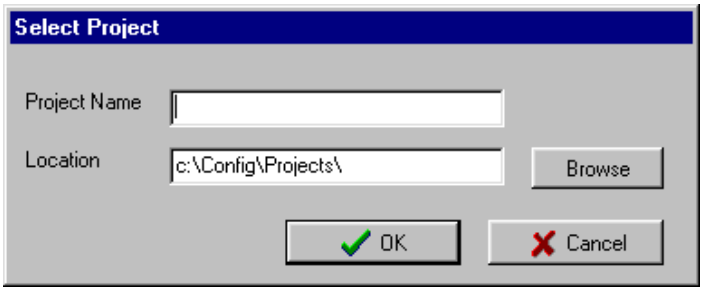


4.3.2 Program Operation

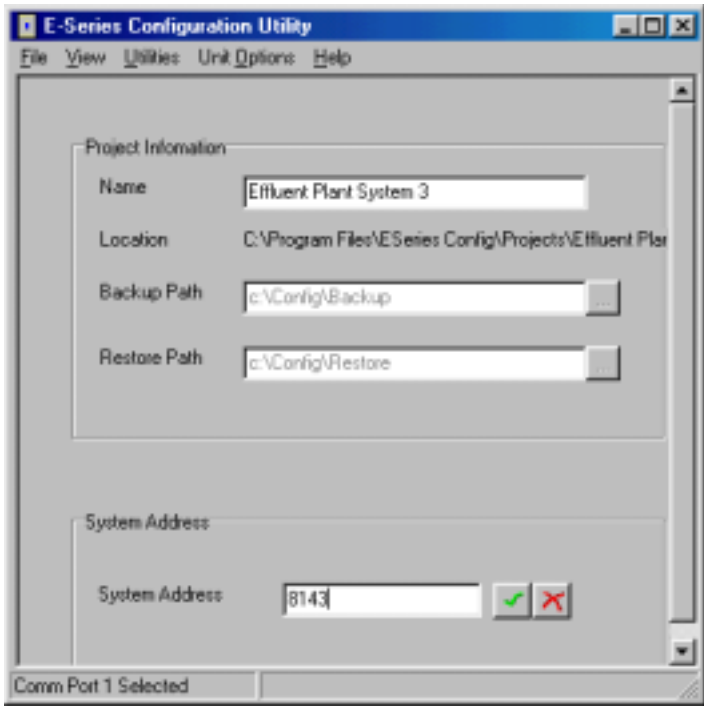
Start the software by either clicking on the start bar and navigating to the Configuration menu or by running ESERIES.EXE in the directory selected in the setup stage.

The Initial screen will appear. The configuration is performed for a complete system. The necessary configuration stages are :

- select system name and system address
- select individual units and unit addresses
- configure I/O mappings for each unit
- configure user options for each unit
- load the configuration files into each unit.



From the initial screen, you can select an existing project, or start a new project. The name of the project will create a new directory which will eventually contain the configuration files for the modules in this system.



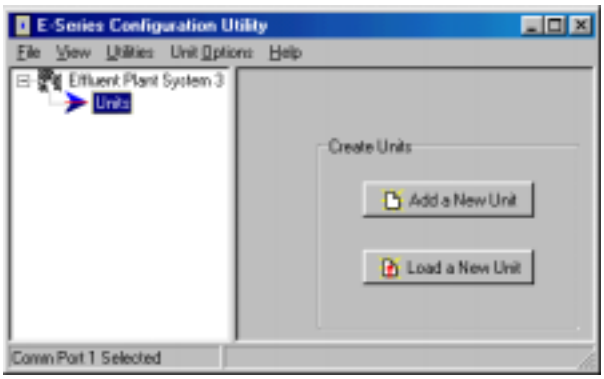
When you have selected the project, a screen will appear where you may enter the system address.

If you are editting an existing project, the system address will already have been entered. Do not change the system address unless you are going to re-program all of the modules in the system.

Double-click on the project name on the menu on the left side of the screen. “Units” will appear. You can now enter the types of units which will be used in the system. If you double-click on “Units”, then the modules that have already been selected will appear.

Loading configuration from an existing module

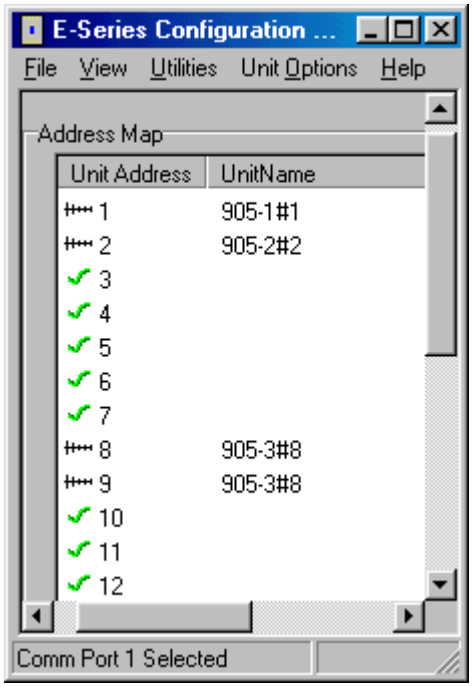
To load the configuration from a module, connect the module to the PC via the RS232 cable and click on "Load Unit". This will allow you to view the module configuration, change it, or copy it for another module - refer to section 4.3.3 for more information.



Adding a new module to the system configuration

To add a new module to the system configuration, click on "Units" on the left-hand menu and then "Add Unit". Select the type of module from the list.

Note that this program covers 105U, 105S and 905U modules. These modules are essentially the same as far as configuration is concerned. That is, a 105-1 or a 905-1 selection will configure a 105U-1, 105S-1 or a 905U-1.

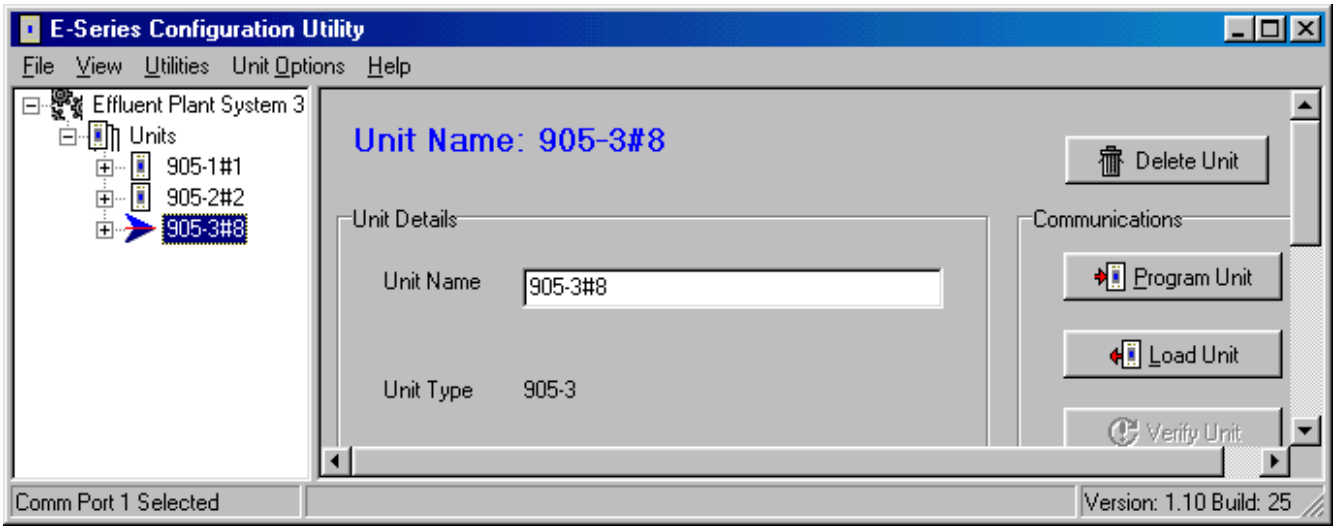


The program will ask to select the unit address and will display the list of available addresses for you to select. For 905U modules, select an address between 1 and 95. For 105S modules, select an address between 96 and 127.

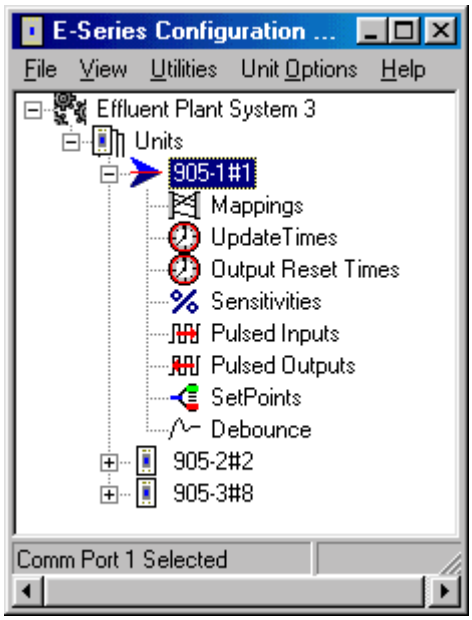
The default name for a unit will include the unit address. For example, "905-3#8" is a 905U-3 module with unit address 8 (and also 9, as a -3 takes two unit addresses). You can change the name of a unit - for example, you could replace the default name with "Pump Station 14".

Deleting a Unit

A module can be deleted from the configuration by highlighting the unit and selecting "Delete Unit".



Configuring an individual module

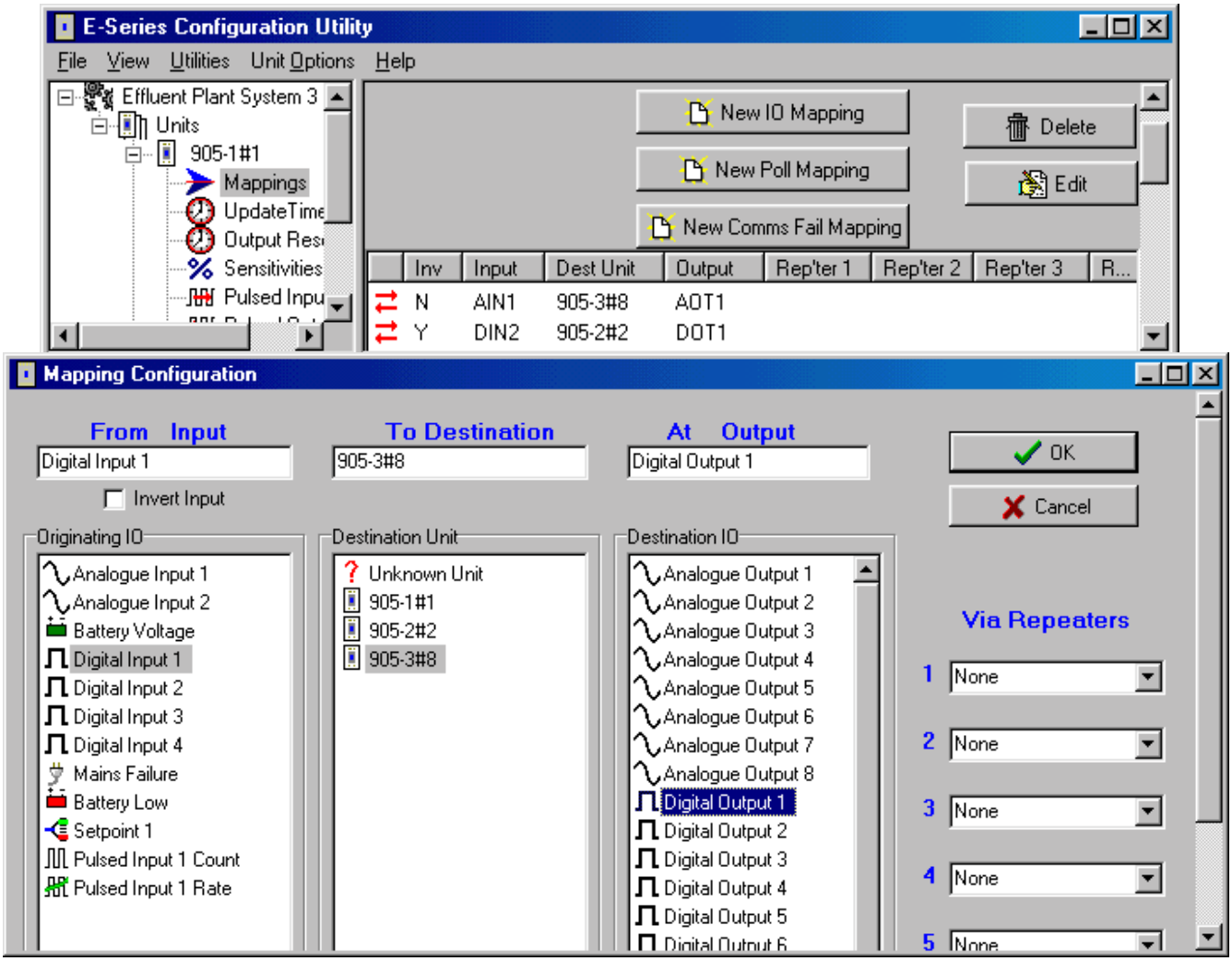


Double-click on a unit shown on the left-hand menu. The configuration options for each unit will appear. We recommend that you configure I/O mappings first, and then other options.

Select "Mappings" and the following screen appears. There are three types of mappings:

- I/O mappings which link inputs to outputs
- Poll mappings, which enables a module on start-up to request set its outputs quickly
- Comms Fail mappings, which maps communication failure status to an output on the local module.

I/O Mapping To enter an I/O mapping, select "New I/O Mapping".



1. The I/O mapping display will show all inputs at the selected module - both physical inputs and internal inputs. Select the input to be mapped.

2. If you wish to invert the mapping, select the "Invert Input" box. If you invert an input, then the output will be the reverse of the input. Analog I/O can also be reversed - 0mA will be 24mA, 4mA will be 20mA etc. **Do not invert pulse inputs.**

3. The invert function is not available on -2 modules - only inverted digital inputs are available (as internal inputs on the input list).

4. To select the destination module, you can either select the module from the "Destination Unit" list, or enter the unit address in the "To Destination" box. You can enter an address that has not yet been allocated to another unit.

5. You can select the output by entering the output number (1 – 8) in the "output" box, or select an output from the displayed list. There will only be a list of possible outputs displayed if at step 2 you selected a desrtination until that has already been configured in the system. The output numbering for each module is:

	105-1	**105-2**	**105-3 First addr (Even)**	**105-3 Second addr (Odd)**	**105-4 First addr (Even)**	**105-4 Second addr (Odd)**
Output 1	DO 1	DO 1	D/P O 1	AO 1	D/P O 1	DIO 5
Output 2	DO 2	None	D/P O 2	AO 2	D/P O 2	DIO 6
Output 3	DO 3	None	D/P O 3	AO 3	D/P O 3	DIO 7
Output 4	DO 4	None	D/P O 4	AO 4	D/P O 4	DIO 8
Output 5	AO 1	None	DO 5	AO 5	DIO 1	DIO 9
Output 6	AO 2	None	DO 6	AO 6	DIO 2	DIO 10
Output 7	PO	None	DO 7	AO 7	DIO 3	DIO 11
Output 8	None	None	DO 8	AO 8	DIO 4	DIO 12

6. If you select a 905U-C as the destination module, you will be asked to select a I/O Register as the destination "output". Note that the grey-shaded I/O registers have already been allocated.

7. Select any intermediate repeater units needed to reach the destination address (entered in order of nearest to furthermost repeater). You can either select from the list of configured units or enter the unit address in the "Repeater" box. If no repeaters are required, do not enter anything in the repeater boxes. If only one repeater address is required, enter the address in box 1 and leave the other repeater boxes empty.

It is possible to configure multiple mappings for an input - each mapping will generate separate transmissions. We recommend that you do not configure multiple mappings to the same output as the output will have the value of the last message that it receives. Each output should have only one mapped input.

It is possible to map a digital input to an analog output - the output will be maximum value when the input is on and minimum value when the input is off. It is also possible to map a analog input to an digital output - the output will be on when the input is equal or greater than 12mA and off when the input is less than 12mA.

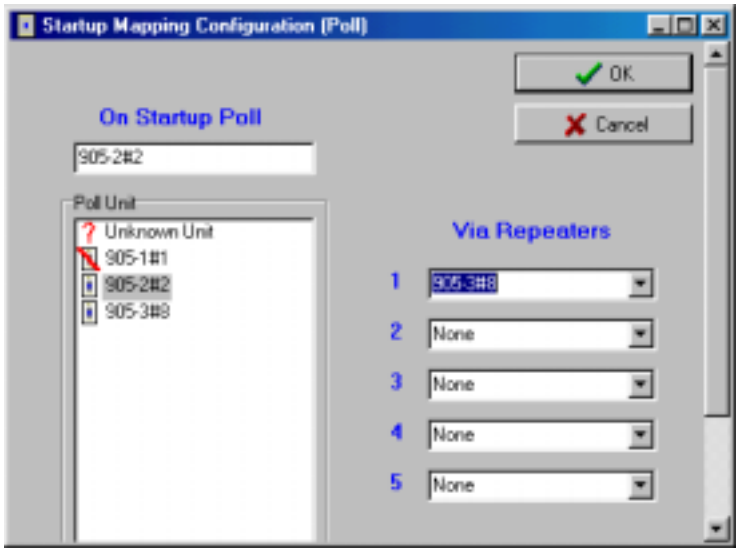
Every module should have at least one mapping configured. If no inputs are being used at this module, map an unused input or an internal input (for example, Low Volts). Map the input to an output which is not being used. If the destination module is a 905U-2, then enter "2" in the "At Output" box - this will allow the only output at the 905U–2 module to be used for something else.

Edit existing mappings

To edit an existing mapping, double-click on the mapping line, or select the mapping line and "Edit".

To delete an existing mapping

To delete a mapping, select the mapping and delete or right-mouse click and select Delete.



Configuring Start-Up Polls

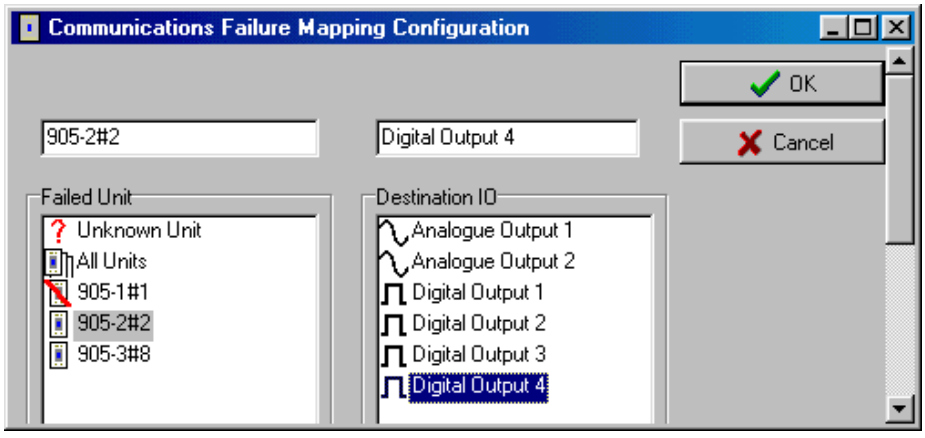
When a unit is first turned on, its outputs will not be set until it receives update messages from other units in the system. To ensure that outputs are set as soon as possible after start-up the unit may be configured to "Poll" any other units with mappings to its outputs.

Select the remote unit to be polled from the unit list, or enter the unit address in the box. If the remote unit communicates via repeaters, select the repeater units or enter the repeater addresses.

Remember that if more than one remote unit is controlling the local outputs, then more than one start-up poll should be configured.

Configuring Comms Fail Mappings

Each module has a "comms fail" status which may be mapped to a local output. The comms fail status is active (on) if the module is transmitting a message and does not receive an acknowledgement after five tries. By setting the comms fail status to a local output, you can provide a communications alarm. The local output can be digital or



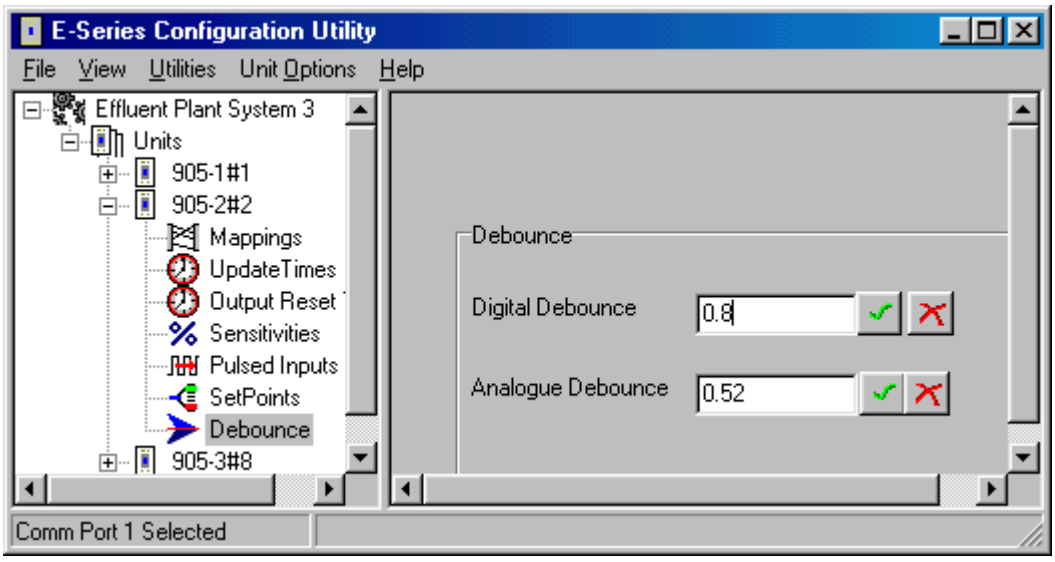
analog - if analog, the output will go to maximum value.

Although communication failure will activate the output, successful comms does not reset the output. You must use the "Reset outputs on comms fail" option (Refer to User Options section).

Each remote module has a separate comms fail status - you enter a separate comms fail mapping for different remote addresses. You can configure several comms fail mappings to the same output - the output will be active if there is comms fail to any of the remote addresses. Configuring a "Comms Fail Address" of zero causes communication failure to any destination module to be indicated on the selected output.

For example, if "Comms fail to unit 12" is configured to DO1, then the module will set (or activate) DO1 each time communications to unit 12 is not successful. If DO1 has a "Reset output" time of 10 minutes configured for DO1, then DO1 will reset (de-activate) 10 minutes after the last comms fail to unit 12.

Debounce Configuration



Debounce is the time which an input must stay stable before the module decides that a change of state has occurred. If a digital input changes (say 0 → 1) and changes again (1 → 0) in less than the debounce time, then the module will ignore both changes. Debounce may be configured for digital inputs on the –1, -2 and -4 modules (0.5 - 8 seconds) and the analog inputs on the -2 module (0.5 - 8 seconds). The default value of 0.5 seconds is suitable for most applications. In applications where a digital input may turn on and off several times slowly (for example, security switches or float switches) a debounce time of up to 8 seconds may be configured. *The configured debounce time has no affect on pulse inputs.*

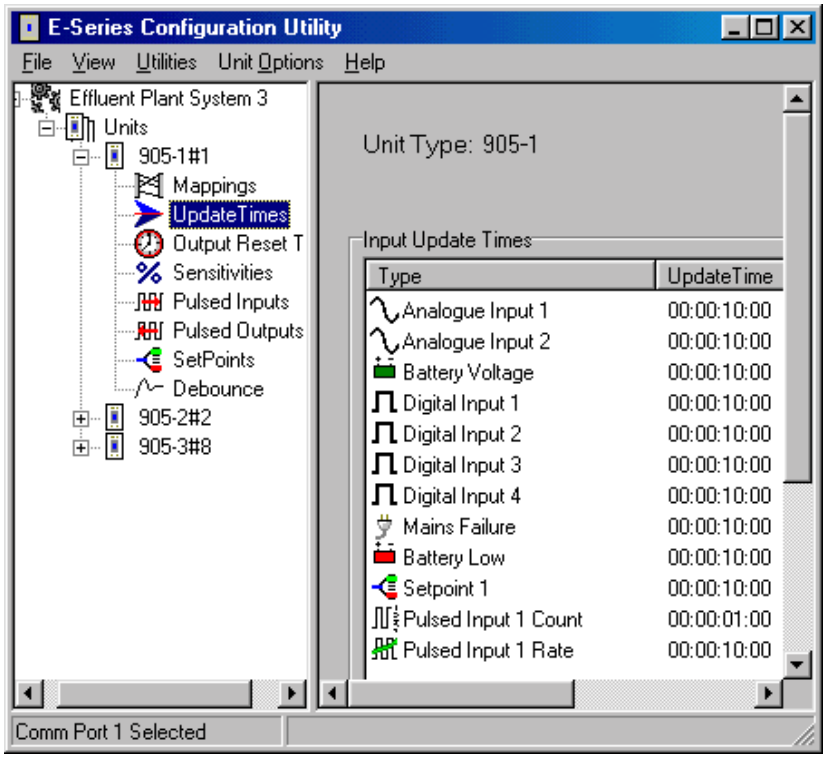
Note that the analog debounce is not configurable for the -1, but is configurable in the -2.

Update Time Configuration

Update messages are sent if a change message has not occurred within the update time period. The update time may be set for each input - both physical and internal inputs.

The default period is 10 minutes for all inputs, except for pulse inputs (1 minute). Short update times should only be used in special circumstances. It is important to remember the principle - "Less radio traffic means better communications". Frequent updates from multiple units causes congestion of the

radio channel, which results in increased communication failures and poorer performance of the system. To change an update time, select "Update Times" on the left-hand menu and double-click the selected input. The update time will be shown in days:hours:minutes:seconds. Change the values in each field. The display also shows the maximum and minimum values. For the -1, -2 and –3 modules, the maximum update time is 16 minutes, however the update time for -4 inputs can be up to 5 days.

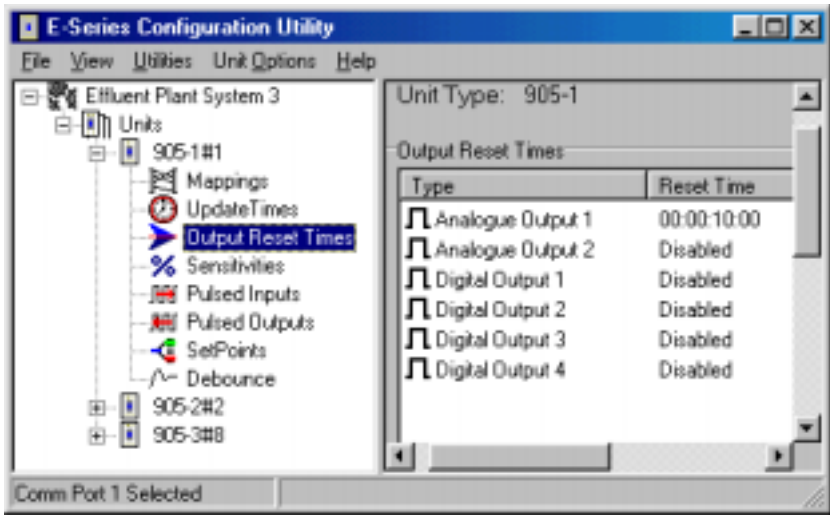


If a zero value is entered as an update time, then the input will not update at all.

Changing Multiple Settings

You can change the Update Times of several inputs simultaneously by using the <Shift> Select feature. For example, if you want to change all digital inputs to 1 minute update, you could change each individually, or you could "block" the four digital inputs using the "Shift" Select feature and select "Edit". You only need to enter the change once to change all of the inputs selected. This feature is also available with the other configurable parameters.

Output Reset Time Configuration



This allows the **Comms Fail Time** to be selected - this is the time for an output to reset if it has not received an update or change message.

Each output on the unit, either analog or digital, may be configured to reset (off or 0mA) when no update transmission has been received for a certain time. This option can be used to ensure that communications failure will not result in loss of control. For example, outputs connected to pumps should be configured to reset on communications failure so that the pump will turn off. The default condition is zero (no reset).

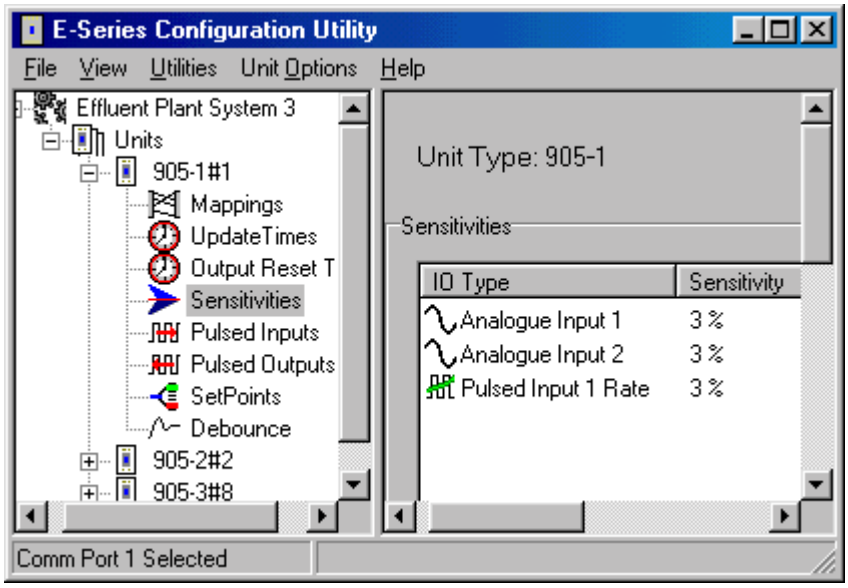
If the reset time is less than the update time, then the output will reset when the reset time expires, and

then set again when the update message is received. We recommend that the reset time be a little more than twice the update time.

To set an output reset time, select "Output Reset Times" on the left-hand menu and double-click the selected input. The update time will be shown in days:hours:minutes:seconds. Change the values in each field. The display also shows the maximum and minimum values.

Analog Sensitivity Configuration

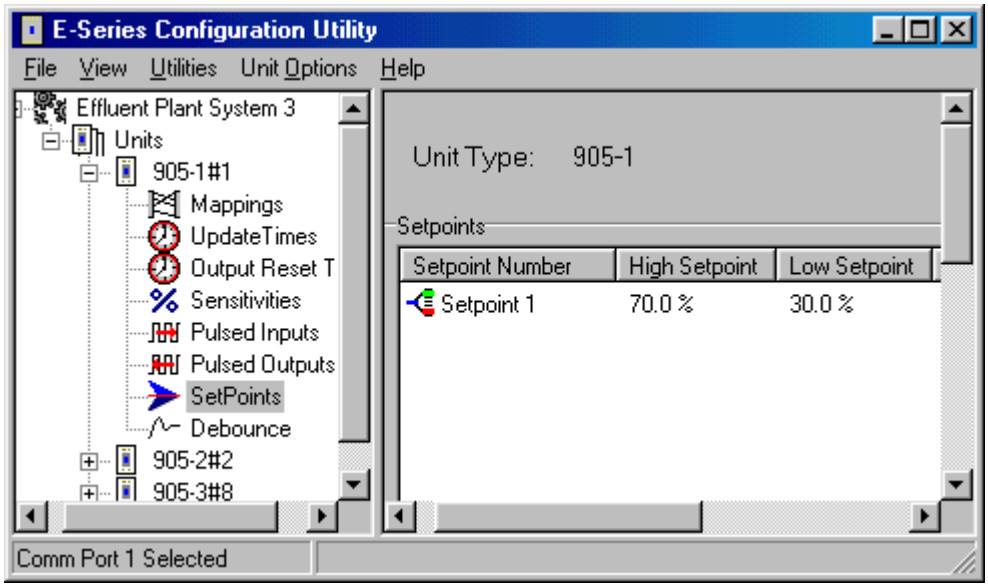
The analog sensitivity is the change required in an analog input before a "Change Of State" is detected, and the new analog value is transmitted. For input signals which vary widely over a short period of time or have a normal oscillation, the analog sensitivity should be set to an appropriately large value. This ensures that many change messages are not transmitted in too short a time. This will result in channel congestion, as described in the preceding section.



To change an analog sensitivity, select "Sensitivities" on the left-hand menu and double-click the selected input. The sensitivity for physical inputs is shown in mA and internal input is shown as %.

SetPoint Configuration

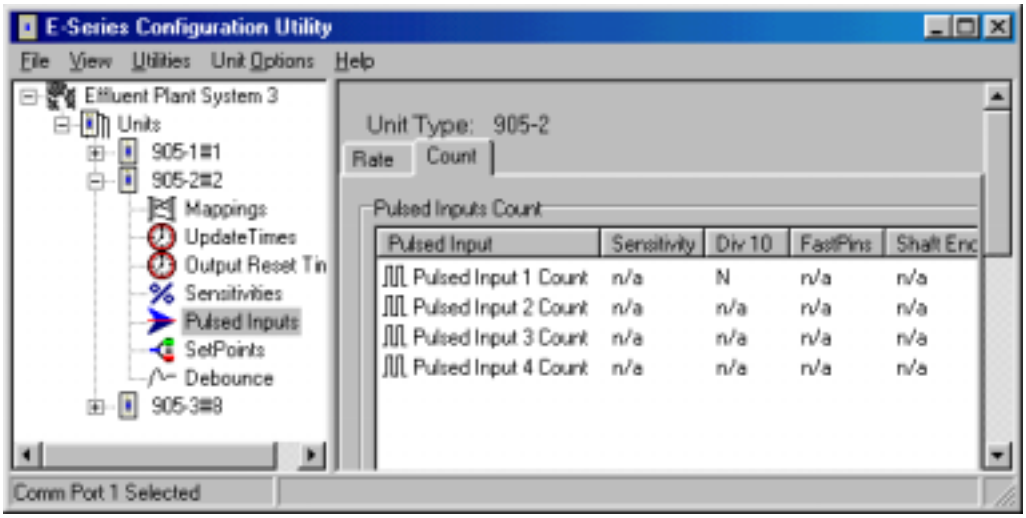
Setpoints allow a remote digital output to be turned on and off depending on the value of an analog input. The "set-point status" internal input must be mapped to an output for this option to have effect. When the AI is less than the Low Set-point (LSP), the set-point status will be active (on, "1") - when the AI is more than the High Set Point (HSP), the set-point status will be reset (off, "0"). Note that the High Set Point (HSP) must always be higher than the Low Set Point (LSP). For the -1 module, only AI1 has set-point values. For -2 modules, all six analog inputs have set-points.



Debounce time operates on the set-point status in the same way as digital inputs.

To change a setpoint values, select "SetPoints" on the left-hand menu and double-click the selected Setpoint Status.

Pulse Input Count Configuration



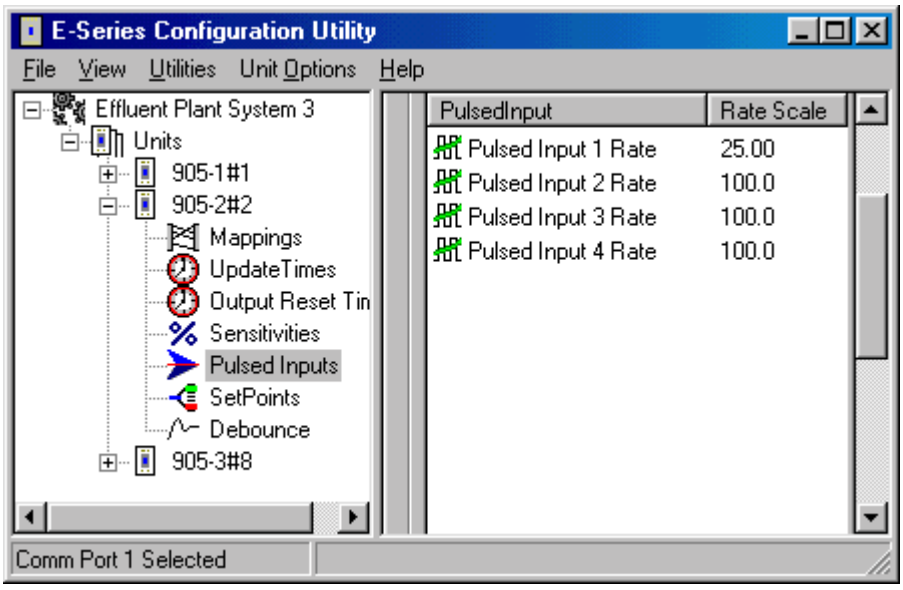
PI1 of the -2 and -4 modules normally count up to 100Hz (as for the other PI's), however can be configured to count up to 1000Hz. This configuration actually divides the input count by 10 - each count in the PI1 register is then equivalent to 10 input pulses. If PI1 is mapped to a PO, then the maximum output pulse rate is 100Hz, however each output pulse is equivalent to 10 input pulses.

To configure the "divide by 10" feature, select "Pulse Inputs" on the left-hand menu and select the "Count" page - double-click "Pulse Input 1 Count" and enable "divide by 10" counting.

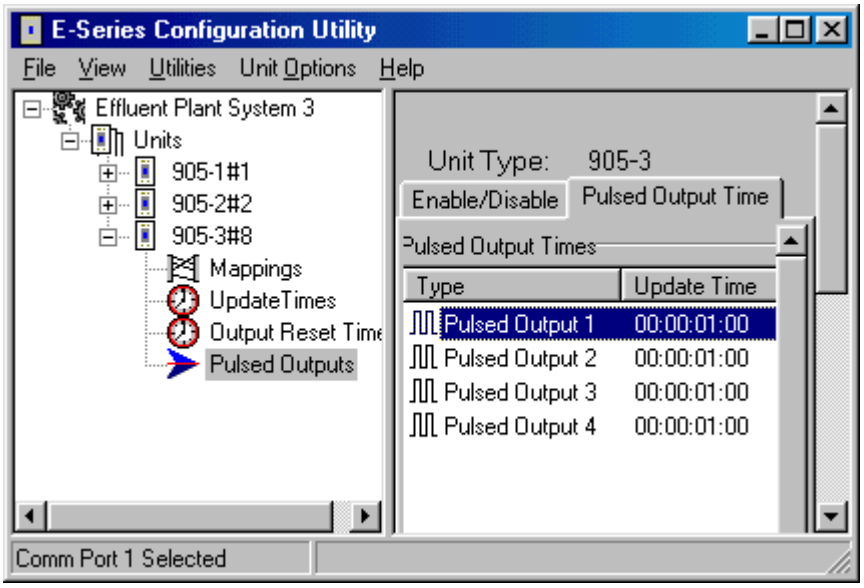
Pulse Input Rate Scale Configuration

When a pulse rate is mapped to an analog output, the rate must be scaled to the 4-20mA output. The pulse rate scale is the rate (in Hz) corresponding 20 mA.

To configure the pulse rate scale, select "Pulse Inputs" on the left-hand menu and select the "Rate" page - double-click the pulse input rate and enter the scale value.



Pulse Output Update Time Configuration

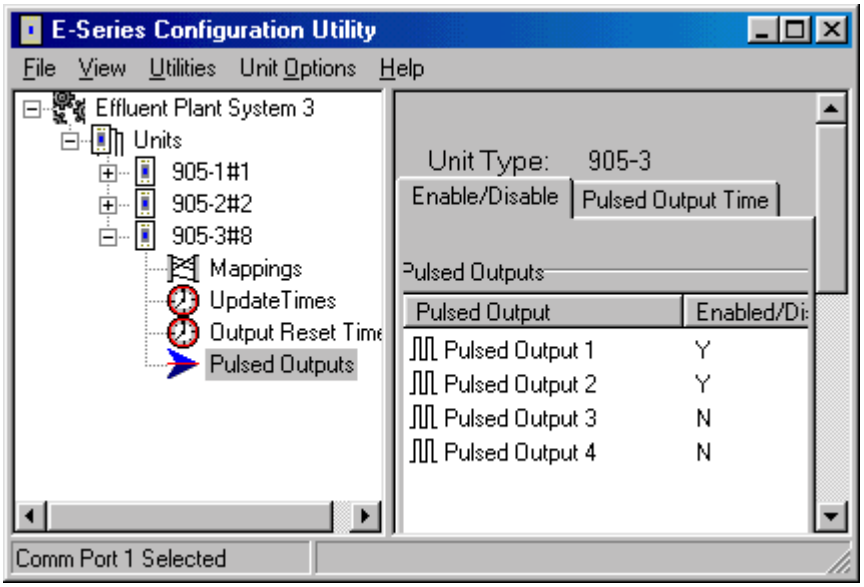


The pulse output update time is the time period over which pulses are output after a PI update is received. It should be configured to correspond to the pulse input update time for the corresponding pulse input. This ensures that the pulse output rate matches as closely as possible the pulse input rate which it is reflecting.

For example, if the PI update time is 1 minute, then the PO update time should also be 1 minute. If the PI update time is changed, then the PO update time at the remote module should be also changed. The PO will still operate if the time is not changed, however pulses may be output faster or slower than the input pulses.

To configure the pulse output time, select "Pulse Outputs" on the left-hand menu and select the "Pulsed Output Time" page - double-click the pulse output and enter the new time.

Pulse Output Enable



The PO's for the -2 and -4 modules are also DO1-4. To use as pulse outputs, you need to enable them as pulse outputs.

To enable pulse outputs, select "Pulse Outputs" on the left-hand menu and select the "Enable/Disable" page - double-click the pulse output to enable.

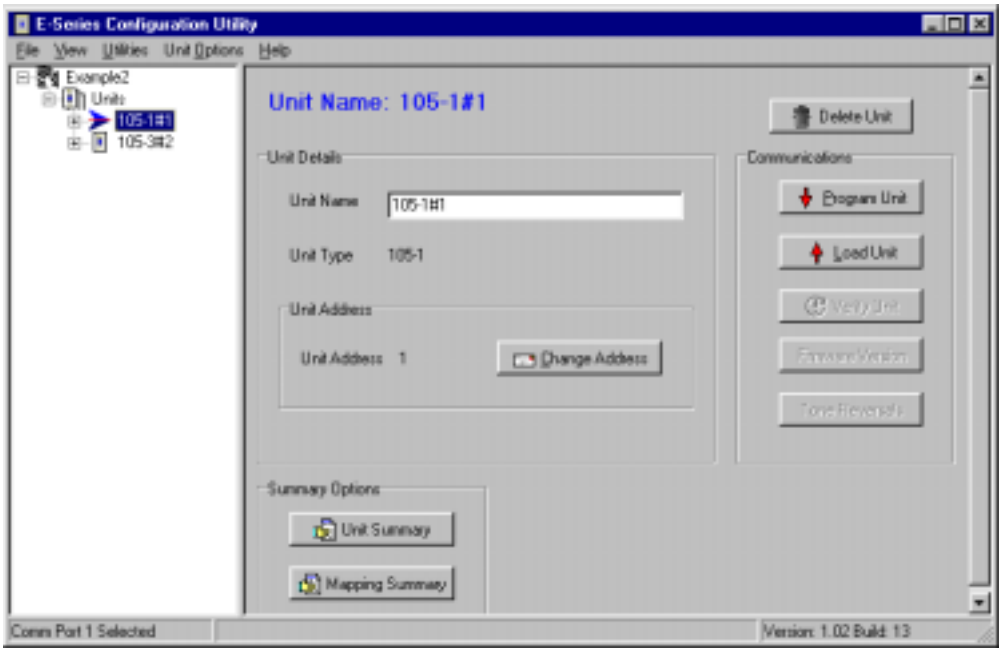
Compiling a System

When you have finished configuring the modules, you should compile the system. The compile function scans the configuration and reports any detected errors. To compile the system, select "Compile System" from the "Utilities" menu. Select the "Compile" button. The system will compile - the display will show if there are any compile errors or warnings.

Programming Configurations to Modules

To program a module :

- Connect the cable from the PC's serial port to the module serial port (see 2.4.10 for cable connections)
- From the Utilities menu, select "Serial Port Setup"
- Select the appropriate serial port (COM1 - COM4)
- Select the unit to be configured from the left-hand menu
- Double-click "Program Unit".



Each module will need to be programmed individually.

4.3.3 Loading Configuration from a Module

Care should be taken when loading a configuration from a module. It is easy to lose the system address and unit address. We suggest that you first view the system address and unit address - you can do this via the "Unit Options" menu. Note these addresses before loading the configuration.

When you upload the configuration, the program will check if you want to load the addresses from the module. **If you do not, then the system address and unit address will change.**

4.3.4 Print Options

You can obtain a print-out of each module configuration. On each unit display, there are "Unit Summary" and "Mapping Summary" windows. Each of these will display a printable information page about that module. The Unit Summary page will display the user options configured, and the Mapping Summary will display the mappings entered for that unit.

The printer may be selected from the Printer Setup option in the File menu.

Chapter Five SPECIFICATIONS

General		
EMC approval	FCC Part 15A	
Radio standards	FCC Part 15.247	902 – 928 MHz, 1W
Housing	130 x 185 x 60mm DIN rail mount	Powder-coated, extruded aluminium
Terminal blocks	Removable	Suitable for 2.5 mm^2 conductors
LED indication	Power supply, OK operation, digital I/O, RX and TX	
Operating Temperature	-40 to 55 degrees C	
Humidity	0 – 99% RH non-condensing	
Power Supply		
Battery supply	11.3 - 15.0 VDC	
AC supply	12 - 24 VAC, 50/60 Hz	Overvoltage protected
DC supply	15 - 30 VDC	Overvoltage and reverse voltage protected
Battery Charging circuit	Included	for 1.2-12 ahr sealed lead acid batt
Solar regulator	Included	Direct connection of solar panel (up to 30W) and solar battery (100 Ahr)
Current Drain at 12VDC	85 mA quiescent for 'U' 45 mA quiescent for 'S'	+ 10 mA/active digital input + 25 mA/active digital output + 2 x analog I/O loop (mA)
Radio transmitter inrush at 12VDC	350mA	
Analog loop supply	Included, except -4	24V DC 150 mA
Mains fail status	Monitored	Can be transmitted to remote modules
Battery voltage	Monitored	As above
Radio Transceiver (905U)		
Spread spectrum	Frequency hopping	16 hop sequences x 100 channels
Frequency	USA/Canada Australia New Zealand	902 – 928 MHz 915 – 928 MHz 922 – 928 MHz
Transmission Power	1W	
Signal detect / RSSI	-120 to –50 dBm	

Expected line-of-sight range (subject to local conditions)	20 miles + @ 4W ERP 15 km + @ 1W ERP depending on local conditions	USA / Canada Australia / New Zealand Range may be extended by up to 5 intermediate modules as repeaters
Antenna Connector	Female SMA coaxial	
Data transmission rate	19200 baud	
Serial Ports		
RS232 Port	DB9 female DCE	9600 baud, no parity, 8 data bits, 1 stop bit
RS485 Port	2 pin terminal block	9600 baud, no parity, 8 data bits, 1 stop bit, Typical distance 1 mile / 2km
Data transmission	On change-of-state + integrity update	Update time configurable
Protocol - serial - radio	asynchronous ARQ, with 16 bit CRC synchronous ARQ	Automatic acknowledgements with up to 4 retries
Communications fail status	May be mapped to local or remote output	Resetting of outputs on comms fail configurable
Inputs and Outputs		
Digital Inputs	905U/105S-1 Four 905U/105S-2 Four 905U/105S-3 None 905U/105S-4 Four plus 12 selectable I/O	Opto-isolated (5000V)inputs, suitable for voltage free contacts or NPN transistor, contact wetting current 5mA, input debounce 0.5 second For –4 modules, as above, but with 3000V surge protection instead of opto-isolation
Digital Outputs Digital Outputs	905U-1/105S-1 Four 905U-2/105S-2 One 905U-3/105S-3 Eight 905U-4/105S-4 Four plus 12 selectable I/O	Relay output contacts, normally open, AC 5A 50V DC 2A 30V, 5A 20V

Pulse Inputs	905U-1/105S-1 One 905U-2/105S-2 Four 905U-3/105S-3 None 905U-4/105S-4 Four	Uses DI1. Max rate 100Hz, min. off-time 5msec. Uses DI1-4. Max rate of DI1 is 1000Hz, min. off-time 0.5msec Max rate of DI2-4 is 100Hz, min. off-time 5msec.
Pulse Output	905U-1/105S-1 One 905U-2/105S-2 None 905U-3/105S-3 Four 905U-4/105S-4 Four	FET output, 30 VDC 500mA max Max rate for 105-1 is100 Hz. Max rate for 105-3 is 1000 Hz. Pulse signal recreated, pulse rate avail. on analog output, (scaling configurable). Divide-by-10 available for 1000Hz inputs.
Analog Inputs	"floating" differential input, common mode voltage -0.5V to 27V 905U-1/105S-1 Two 4-20 mA 905U-2/105S-2 Six 0-20mA	24 VDC for powering external loops provided, 150 mA max. Digital filter time constant 1 second (config.) Resolution 15 bit, Accuracy 0.1% Resolution 12 bit, Accuracy 0.1%
Analog Input Setpoints	905U-1/105S-1 AI 1 only 905U-2/105S-2 AI 1-6	Configurable high & low set-points, allowing set/reset of remote digital outputs
Analog Outputs	current sink to common 905U-1/105S-1 Two 4-20mA 905U-3/105S-3 Eight 0-20mA	max loop voltage 27V, Resolution 15 bit, Accuracy 0.1% Resolution 12 bit, Accuracy 0.1%
System Parameters		
Network Configurations	Communications via radio or RS485 or network of both	Up to 95 radio units with up to 32 serial units off each radio unit
Mapping	Any input to any output in system	
User Configuration		RS232 PC or laptop

Diagnostics		
On board diagnostics	Automatic check on start-up Via RS232 terminal or laptop	Input status Output test Incoming radio signal level Simple radio path testing

Chapter Six TROUBLESHOOTING

6.1 Diagnostics Chart

INDICATOR	CONDITION	MEANING
OK LED OFF	Continuously	• Battery Voltage low • CPU failure • +24V supply failure/overload
OK LED ON	Continuously	• Normal Operation
PWR LED ON	Continuously	• Supply available from SUP1/SUP2 • Supply available from solar panel
TX LED ON	Flashes briefly	• Radio transmitting
RX LED ON	Flashes briefly	• Radio Receiving • Serial port communicating
RX LED ON	Flashes continuously	• Module in Configuration Mode
RX LED ON	Continuously	• Test Button press in Configuration Mode
No transmission on change of state		• Unit not configured correctly - re-configure and check operation

The green OK LED on the front panel indicates correct operation of the unit. This LED extinguishes on failure as described above. When the OK LED extinguishes shutdown state is indicated. In this state, all digital outputs turn OFF and the +24V supply turns off.

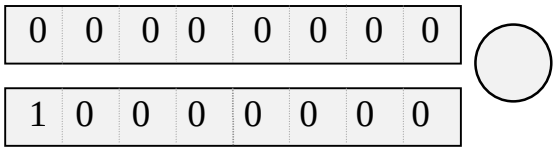
On processor failure, or on failure during start-up diagnostics, the unit shuts down, and remains in shutdown until the fault is rectified. The unit also shuts down if the battery voltage falls below 10.8 volts. This is a protection feature designed to protect the battery from deep discharge in case of extended period without supply voltage.

6.2 Self Test Functions

6.2.1 Input to Output Reflection (905U-1/105S-1 only)

The unit will require re-configuration after SELF TEST. Ensure you know the required operational configuration including system and unit addresses so that the network can be restored after testing.

Remove the cover in the front panel, and set the DIP switches as shown below. Hold down the red button for five seconds, or until the Rx LED glows yellow, release the Red button (the Rx LED now flashes), then press and release the Red button (the flashing Rx LED extinguishes).



Input signals may now be connected to the input terminals of the module. If the module is operating correctly, then the input signals will be reflected to the corresponding output on the same module. For example, if DI 1 is connected to common - i.e. the first digital input is turned "ON" - then DO 1 will activate, if the module is functional. Similarly, if a 12mA signal is connected to AI 2, then a 12mA signal should be able to be measured from AO 2, if the module is functioning correctly.

If a module does not pass its self test function, then it should be returned to an authorised service agent for attention

6.2.2 Radio Testing using Tone Reversals (905U modules only)

This function allows the unit to be configured to continuously transmit a sequence of alternate zeros and ones on the radio. This function provides the facility to check VSWR of antennas during installation, as well as checking the fade margin of the path between two units (see below - received signal strength indication).

The tone reversals function is initiated by setting all of the DIL switches to ON, and holding down the red button for approximately 5 seconds(until the RX LED lights continuously). On releasing the button, the RX LED will flash continuously, and the TX LED will light, indicating that the radio transmitter is on.

To finish the test, push the red button again or re-power the module.

6.2.3 Diagnostics menu

To aid in the checking and set-up of the 105 unit, a user friendly menu provides access to diagnostic functions in the 105. Use of the diagnostics menu does not affect module configuration. To access these diagnostics, a terminal must be connected to the serial port on the unit. The terminal may be a standalone terminal, or a personal computer running terminal emulation software such as Hyperterminal, which is supplied as part of MS Windows 95, 98, 2000, ME and NT (normally accessible through the Accessories / Communications menus).

Start Hyperterminal (Hypertrm.exe) and set up a “new connection” (call it “905U”) - under the “Connect Using” prompt, select “Direct to COM1” or “Direct to COM2” depending on which COM port you will be using on the PC, then select the following Port Settings - 9600 baud, 8 data bits, no parity, 1 stop bit, no flow control. Save this connection for future use - this means that you won’t

have to set up the connection parameters for future uses.

Connect the module (ensure the RS485 port is disconnected first) to the PC using the same serial cable used for configuration. The diagnostics menu is accessed by setting all switches to ‘0’, and holding down the red button for approximately 5 seconds, until the RX LED lights continuously. One of the following menus will be displayed on the terminal :

105 V1.0
a) Ins
b) Tones
c) Comms
d) DO1
e) DO2
f) DO3
g) DO4
h) AO1
i) AO2
j) Switch
k) Signal
>

1052 V1.0
a) Digital Ins
b) Analog Ins
c) Tones
d) Comms
e) DO1
f) Switch
g) Signal
>

1053 V1.0
a) Ins
b) Tones
c) Comms
d) DO1
e) DO2
f) DO3
g) DO4
h) DO5
i) DO6
j) DO7
k) DO8
l) AO1
m) AO2
n) AO3
o) AO4
p) AO5
q) AO6
r) AO7
s) AO8
t) Switch
u) Signal
>

1054 V1.0
a) D Ins
b) A Ins
c) Tones
d) Comms
e) DO1
f) DO2
g) DO3
h) DO4
i) DIO1
j) DIO2
k) DIO3
l) DIO4
m) DIO5
n) DIO6
o) DIO7
p) DIO8
q) DIO9
r) DIO10
s) DIO11
t) DIO12
u) Signal
>

Choose an item from the menu by entering the letter before that item. For example, to select the "Comms" function from the “-2” Menu, enter :- d

Inputs

This option provides a dynamic display of the status of all of the inputs in the 105, both internal and external.

905U-1/105S-1 Modules

1234MLS	P CNT	AI1	AI2	P RATE	VBATT
0101001	00F6	C000	4000	8000	9C00

The first 7 values (1234MLS) each represent a single digital input. A ‘1’ indicates that that input is ON, and a ‘0’ indicates that the corresponding input is OFF. "1234" represents the four physical digital inputs, DI1 to DI4. "M" is the mains fail status (‘1’ for mains fail, ‘0’ for mains OK). "L" is the battery

low volts status (‘1’ for low volts ‘0’ for OK). "S" is the set-point status.

P CNT, AI1, AI2, P RATE, and VBATT each represent 16 bit values, displayed as four hexadecimal digits.

P CNT is the current value of the pulsed input counter. This value should increment each time ‘DI 1’ turns from OFF to ON. P RATE displays the current pulse rate at DI1. This value is scaled according to the MAXRATE value configured (0 Hertz is displayed as 4000, and the maximum rate is displayed as C000).

AI1 and AI2 represent the value for the two analog inputs. Full scale input (20 mA) is displayed as C000, 4mA is displayed as 4000, and 0ma is displayed as 2000. Analog inputs are filtered digitally with a time constant of 1 second, so a sudden change in the analog input current will result in a slower change in displayed analog value, finally settling at the new value.

A guide to translate the displayed value to the analog input current is provided below.

	Add together the figures corresponding to each digit in each position to determine the current (mA) e.g. displayed value 3456 = 2.000+0.500+0.039+0.003 = 2.542mA			
Digit	**Leftmost position**	**Next position**	**Next position**	**Rightmost position**
0	-	0.000	0.000	0.000
1	-	0.125	0.008	0.000
2	0.000	0.250	0.016	0.001
3	2.000	0.375	0.023	0.001
4	4.000	0.500	0.031	0.002
5	6.000	0.625	0.039	0.002
6	8.000	0.750	0.047	0.003
7	10.000	0.875	0.055	0.003
8	12.000	1.000	0.063	0.004
9	14.000	1.125	0.070	0.004
A	16.000	1.250	0.078	0.005
B	18.000	1.375	0.086	0.005
C	20	1.500	0.094	0.006
D	22	1.625	0.102	0.006
E	-	1.750	0.109	0.007
F	-	1.875	0.117	0.007

VBATT is the current internally derived battery voltage. 4000 corresponds to 8 Volts, C000 represents 16 volts. A quicker method is use the calculation :

Battery voltage (volts) = ½ I + 6, where I is the mA value determined from the above table using VBATT. For example, a value of VBATT of A000 gives an I value of 16mA from the above table. The battery voltage corresponding to this is 14V (or ½ x 16 + 6).

905U-2/105S-2 Modules

Digital Inputs

DIN	SETPNT	PULSED			
1234	MSL123456	PIN1	PIN2	PIN3	PIN4
0000	100111111	0000	0000	0000	0000

Analog Inputs

VBAT	PR1	PR2	PR3	PR4	AI1	AI2	AI3	AI4	AI5	AI6
8138	4000	4000	4000	4000	0D3A	0CD2	0CC7	0CC7	0CD4	0CC7

905U-3/105S-3 Modules

ML	VBAT	VSLR
00	9FA2	0000

905U-4/105S-4 Modules

Digital Inputs

DIN	DIO			PULSED			
1234	123456789	ABC	MLS	PIN1	PIN2	PIN3	PIN4
1001	010101010	001	101	0001	0001	0001	0001

Analog Inputs

VBAT	PR1	PR2	PR3	PR4
8DBE	0000	0000	0000	0000

Tones (905U modules only)

This provides the same function as described above in 6.2.2. Tone Reversals. This function may be used to check VSWR of antennas, and may be used in conjunction with the Signal option (described below) to check the path between two units.

Comms

This function allows monitoring of all messages transmitted and received over the radio. Transmitted messages are displayed starting in the leftmost column of the display. Received messages are displayed with the received signal strength preceding the message. The first four hexadecimal digits are the system address attached to the message, and must match for units to communicate successfully.

The received signal strength is in negative dBm - the lower the measurement, the stronger the radio signal. A measurement larger than 95 indicates a weak radio signal.

Example (105-1):

>c

Comms

TX: 01FA8106008005C6727D44	Command message transmitted by this unit.
84 01FA8186C6E0E3	Acknowledge received from remote.
81 01FA860100800100009286	Message received from remote unit.
TX: 01FA868100FCE4	Acknowledge message from this unit to remote.

DO1 to DO8, DIO1 to DIO12

These options allow the user to set and clear digital outputs. To set an output, select the corresponding menu item, at the prompt, type the value FFFF to turn the output ON, or 0000 to turn the output OFF. For example, to set DO1 ON,

>e

DO1

>FFFF

AO1 to AO8

These options allow the user to set analog outputs to any value. To set the output, select the corresponding menu item. At the prompt type the value required for the analog output as a four digit hexadecimal value. Refer to the table above for analog current/expected value relationship. To set AO2 on 105-3 to 19 mA :

>m

AO2

>B800

Switch

This option allows testing of the DIL (Dual In Line) switches. The diagram below indicates the layout of the switches of which there are two sets of eight, with an "Enter" button located to the right of the pair. the display indicates the current switch settings with the digit '1' corresponding to 'On' and the digit 'O' corresponding to 'Off'. Changing the switch settings in this mode will change the display. Test each switch and check to ensure the display changes accordingly.

Switches	**Displayed**
1 1 1 0 0 0 1 0	1110001001010101
0 1 0 1 0 1 0 1	

Signal

This option provides for testing the radio path between two 905U units for a suitable reliability margin. Although a pair of units may communicate successfully, radio communication may be affected by a range of influences, including atmospheric conditions, changing landscape, degradation of antennas or co-axial cable, low battery voltage etc. “Fade margin” is an indication of how far a radio path can deteriorate before communication becomes unreliable.

When using the Signal feature, the current received radio signal level is displayed in negative dBm (dBm is relative to 1mW of RF power). A display of 100 means –100dBm. This means that a stronger signal will have a lower measured value.

To check the radio path between two units, select the signal option at the local unit. The display will initially show the background noise of the radio band. Determine the approximate average of the noise level. The remote unit may then be set up for tone reversals (refer 1 above). Determine the approximate average of the received signal strength. It is normal for the measured values to continually change - the radios are continually changing frequency. Calculate the best average for both the noise and signal. For a reliable radio path, the signal strength must be at least 10dB lower than the noise level, or 95, whichever is less.

For example, if the noise level is 120, then the radio signal must be 95 or lower for a reliable path. If the noise level is 100, then the radio signal must be 90 or lower.

A simpler method when remote units are not easily accessible is to cause a transmission from the local unit to the remote unit (by setting a digital input which maps to the remote unit, for example). The meter will latch the received signal from the remote unit for half a second, allowing the received level to be read.

If any obstructions in the radio path are likely to change, then this should be allowed for. For example, if the radio test is done during winter and the radio path is through trees without leaves, then another 10dB of margin should be allowed for to cover summer conditions when the trees have leaves.

When using directional antennas (i.e. YAGI antennas) this feature may be used to peak the received signal level. Set-up the remote unit to transmit tone reversals as described above, and observe the signal indication while adjusting the orientation of the antenna. A peak in signal level indicates optimum orientation of the antenna.

Chapter Seven WARRANTY & SERVICE

We are pleased that you have purchased this product.

ELPRO products are warranted to be free from manufacturing defects for a period of 2 years from the effective date of purchase. The effective date of purchase is decided solely by ELPRO Technologies.

This warranty does not extend to:

- failures caused by the operation of the equipment outside the particular product's specification, or
- use of the module not in accordance with this User Manual, or
- abuse, misuse, neglect or damage by external causes, or
- repairs, alterations, or modifications undertaken other than by an authorised Service Agent.

ELPRO's liability under this warranty is limited to the replacement or repair of the product. This warranty is in lieu of and exclusive of all other warranties. This warranty does not indemnify the purchaser of products for any consequential claim for damages or loss of operations or profits and ELPRO is not liable for any consequential damages or loss of operations or profits resulting from the use of these products. ELPRO is not liable for damages, losses, costs, injury or harm incurred as a consequence of any representations, warranties or conditions made by ELPRO or its representatives or by any other party, except as expressed solely in this document.

Full product specifications and maintenance instructions are available from your Service Agent, your source of purchase, or from the master distributor in your country upon request and should be noted if you are in any doubt about the operating environment for your equipment purchase

In the unlikely event of your purchase being faulty, your warranty extends to free repair or replacement of the faulty unit, after its receipt at the master distributor in your country. Our warranty does not include transport or insurance charges relating to a warranty claim.

Should you wish to make a warranty claim, or obtain service, please forward the module to the nearest authorised Service Agent along with proof of purchase. For details of authorised Service Agents, contact your sales distributor.

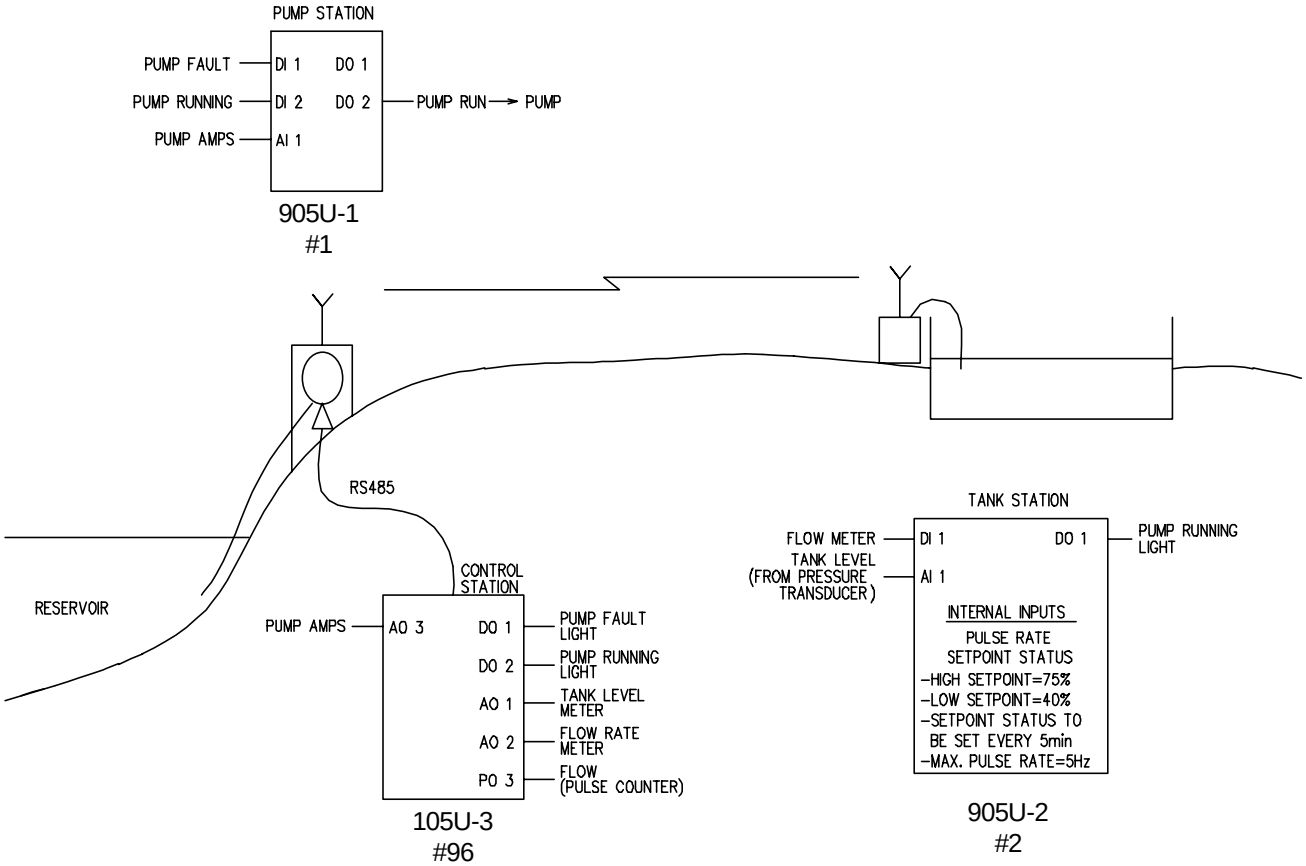
Appendix A SYSTEM EXAMPLE

The following example of a system is a comprehensive guide to using some of the features of the range and design of system.

The example application is a pump station which supplies water from a reservoir to a tank station. Signals are transferred between the pump station and tank station by radio - the distance between the two stations is 10 km (6 mile), and the radio path is heavily obstructed by buildings and trees. A control station is located near the pump station, and there is an existing signal cable between the control station and the pump station.

A 905U-1 module is installed at the pump station (with address 1) and a 905U-2 module is installed at the tank station (with address 2). Because the signal cable to the control station does not have enough cores for all of the signals required, the signal cable is used as a RS485 cable and a 105S-3 module is installed at the control station (with address 96). As this module has an address greater than 95, the 905U-1 at the pump station will communicate to it via its serial port.

The following diagram represents the system :-



The following design points should be noted :-

- A test of the radio path between the pump station and the tank station indicated that the radio path would be reliable provided antennas were installed at 6 m above the ground. At each site, the coaxial cable would be approx 30 feet in length, so it was decided to use 6 element Yagi antennas with RG58 coaxial cable - the Yagi antennas would compensate for the loss in the cable.

- At the tank station, there was an existing light pole with a mains power supply - the light pole was 10m high. Permission was obtained to mount the antenna from the pole and to use the power supply for the radio telemetry module.

  As there was no existing electrical panel at this station, a small steel enclosure was installed on the light pole. A 2 Amp-Hour sealed battery was installed to provide power during any mains failure. The flow and level transducer were powered from the 24VDC loop supply provided by the module.

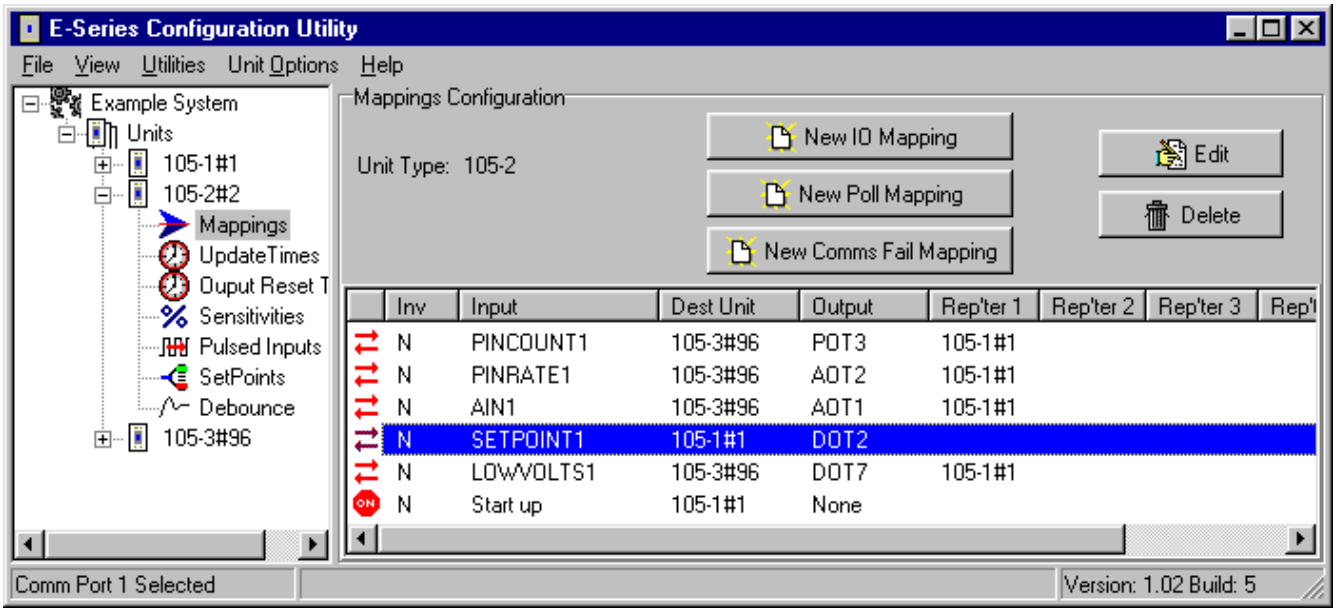
- At the pump station, the antenna was mounted on a 10' J-bracket installed on the roof of the pump station building. The final height of the antenna was approx 20 feet. Care was taken to align the Yagi antennas so they pointed at each other. The Yagi antennas were installed with horizontal polarity - that is, with the elements horizontal. These antennas will not "hear" other radio users on the same radio channel which generally use vertical polarity.

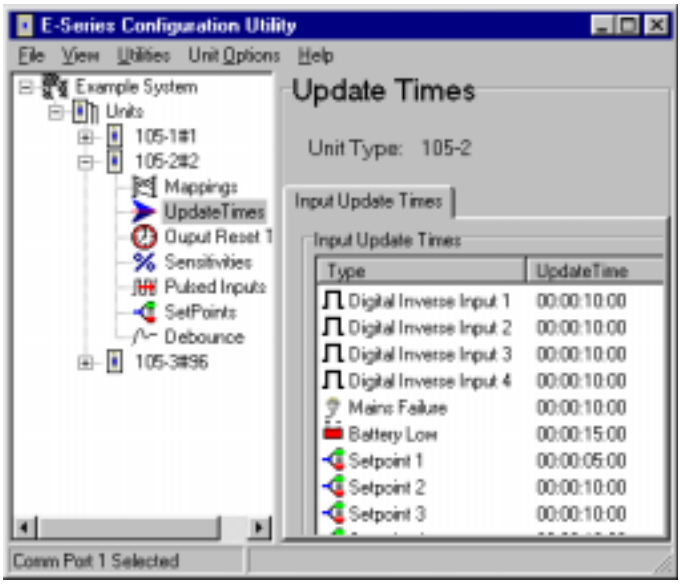
  There was an existing electrical enclosure at the pump station, and the 905U module was installed inside this enclosure. The module was powered from a 24VDC supply with a 2 Amp Hour sealed battery as backup.

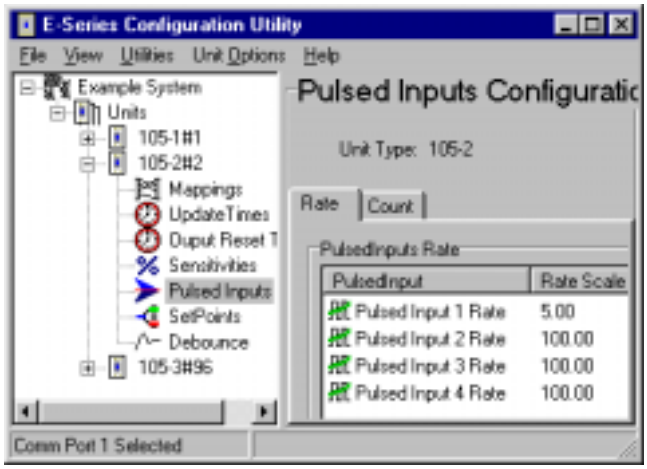
- At the control station, the 105S module was installed inside the existing control panel enclosure. The module was powered from an existing 24VDC power supply.

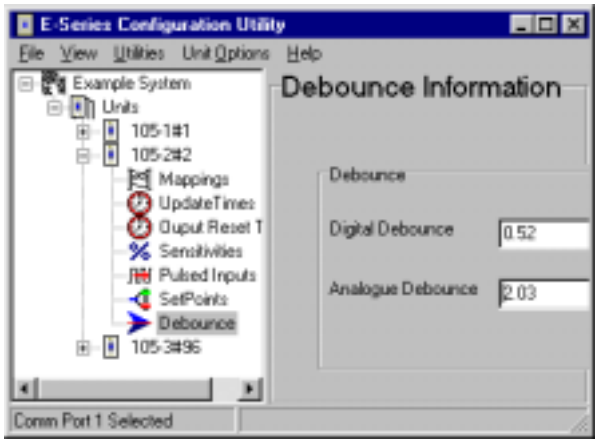
Tank Station Configuration

The 905U-2 module has the following configuration :-









Note the following points in the configuration :

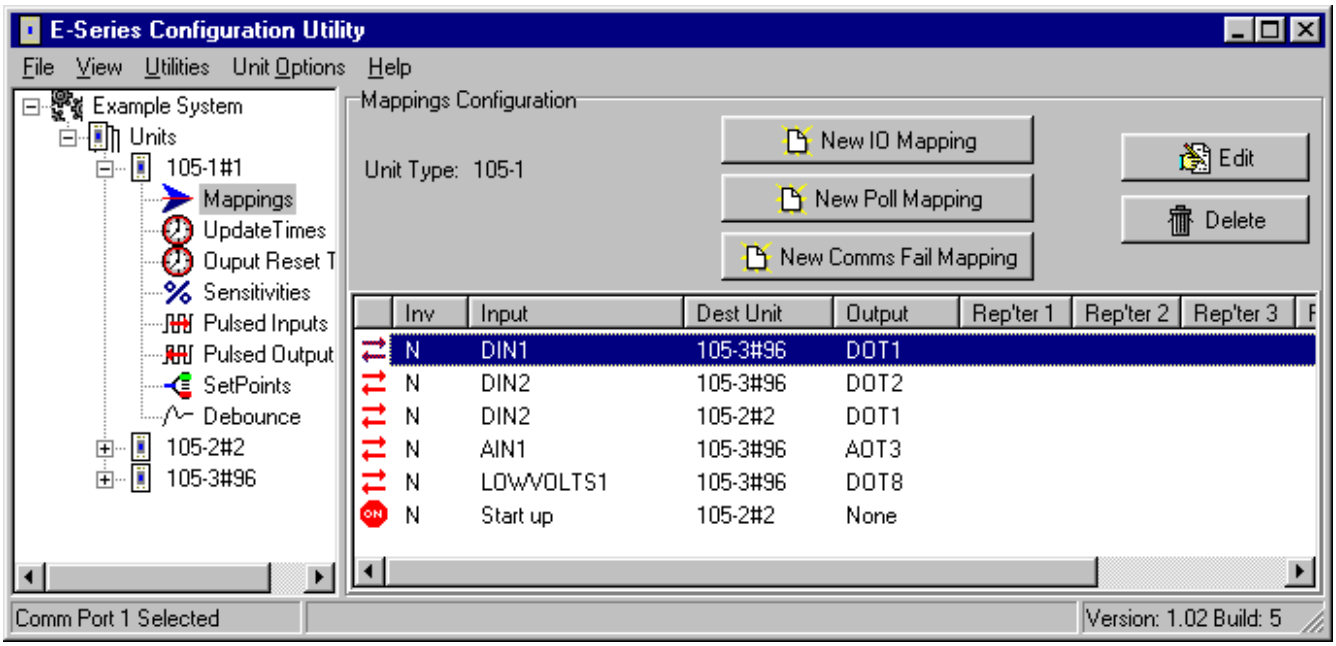
- #1 is a repeater for communications between #2 and #96
- The pulse rate scaling for PIN1 has been set to 5

Hz to match the maximum flow rate of the flow meter. Note that PIN1 has not been configured for "divide by 10" (for 1000 Hz pulse signals).

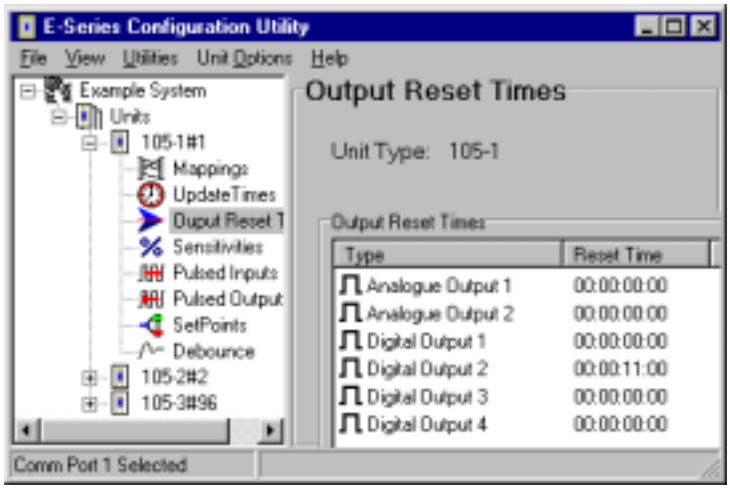
- AIN1 (the level transducer) is mapped to AO1 at the 905U-3. The analog debounce has been set to 2 sec. This is because of concern of wave action on the surface of the tank causing un-necessary change transmissions. This debounce time will also operate on the Pulse Rate value, but as the flow rate changes slowly, this will not affect the performance of this signal.
- SETPOINT1 (the set-point status for AI1) is mapped to DO2 of #1 (pump station). The set-point values for this setpoint have been set to 40% and 75%. When the tank level drops to 40%, DO2 at the pump station will activate to start the pump. When the level rises above 75%, DO2 will reset to stop the pump.
- The update time for SETPOINT1 has been changed to 5 minute, as required.
- An additional mapping has been entered - LOW VOLT has been mapped to DO7 at #96 via #1 (DO7 at the control station). This mapping is for future use - it will provide a low battery voltage alarm for the tank station. The update time for this mapping has been set to the maximum time of 15 minutes to reduce loading of the radio channel.
- A Start-up poll has been configured for #1, as DO1 at the tank station is controlled from the pump station. Note that no comms fail reset time has been configured for DO1. As this output drives an indication only, the indication will show the last correct status even during communication failures.

Pump Station Configuration

The 905U-1 module has the following configuration :-



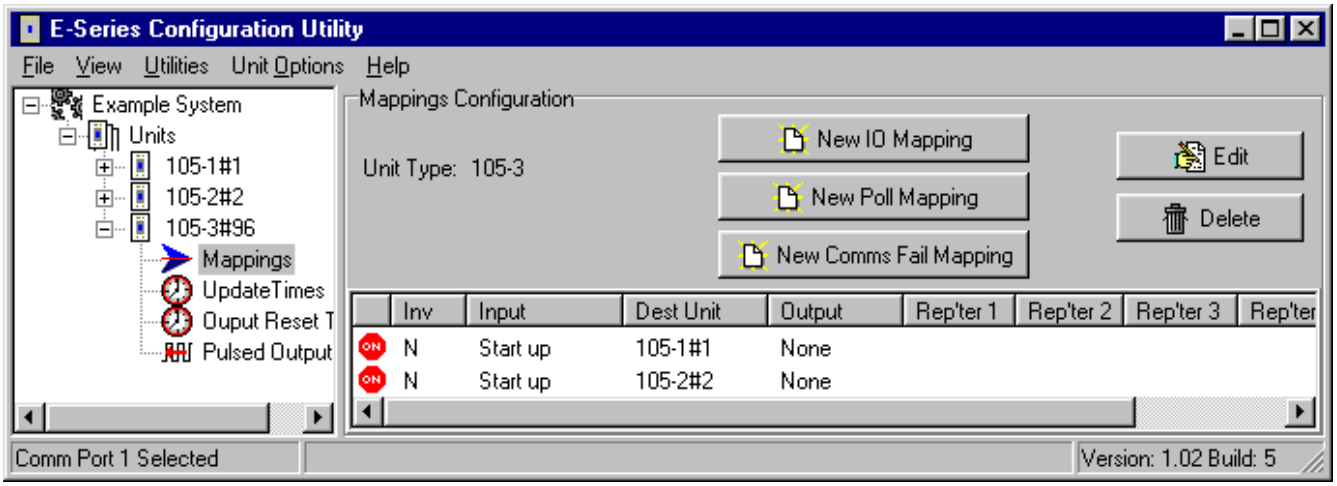
Note the following points in the configuration:



- Note that no repeater address is necessary between #1 and #96.
- DIN2 (pump running signal) has two mappings - a mapping to DO1 at #2 (tank station) and DO2 at #96 (control station). When DIN2 changes, there will be two separate change messages transmitted - one by radio to #2 and one by serial link to #96.
- AIN1 (pump amps) is mapped to AO3 at #97 (control station).
- An additional mapping has been entered - LOW VOLT has been mapped to DO8 at the control station. This mapping is for future use - it will provide a low battery voltage alarm for the pump station.
- A Start-up poll has been configured for #2, as DO2 at the pump station is controlled from the tank station. Note that a comms fail reset time of 11 minutes has been configured for DO2. This means that if a message has not been received for DO2 within 11 minutes, DO2 will reset and switch off the pump. The 11 min time was chosen as it means that two successive update messages have to be missed before the pump is reset, and there is no problems if the pump runs for 11 minutes during a system failure (the tank will not overflow during this time).

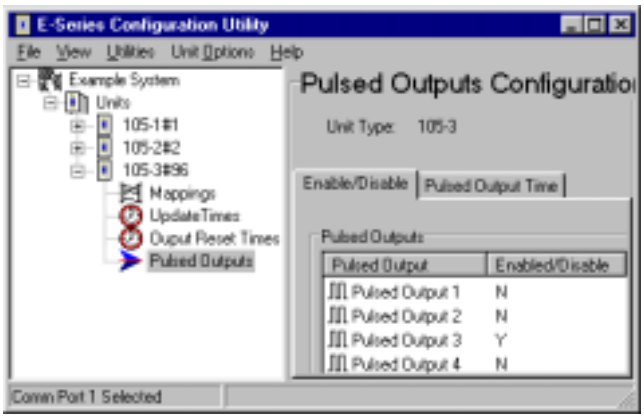
Control Station Configuration

The 105S-3 module has the following configuration :-



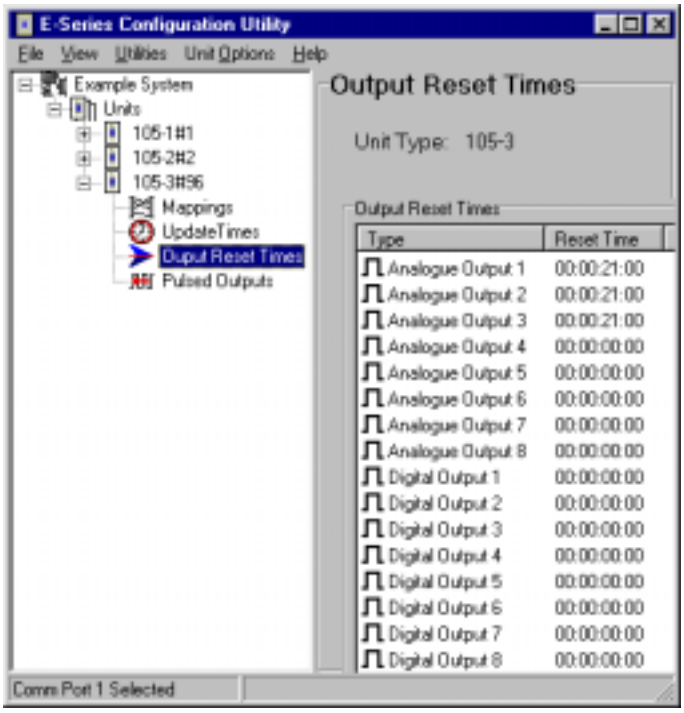
Note the following points in the configuration :

- The only mappings are Start-up polls. Note that there are two separate polls, one for each remote module.



- PO 3 has been configured as a PO. Its pulse output update time is the same as the PI update time at the remote module (both have been left at their default value of 1 minute).
- Reset times have been selected for the analog outputs (21 minutes) but not the digital outputs. In the event of a system failure, the digital outputs will stay at their last correct status, but the analog outputs will reset to 0 mA.

System Failure Alarm



After the system had been running for some time, the operators wanted a "system failure" output at the control station, to warn the operators that there was a fault with the system.

The following configuration was added :

At #2 (tank station), Inverse DI4 → DO4 at #96 via 1 ; DI4 Update time = 1 minute

At #96 (control station), DO4 Comms fail reset time = 3.5 min

At the control station, DO4 was a "system OK" signal. It was normally active - if the signal reset, then this represented a system failure. At the tank station, there is no signal wired to DI4. By mapping Inv DI4 to DO4 at the control station, a message is transmitted every minute to this output to activate it. The message is transmitted via the radio link to #1, and then by the serial link to #96. If anything happened to either module #2 or module #1, or the radio link, or the serial link, then the update messages for DO4 will not be received at the control station module. After 3.5 Minutes, DO4 will reset indicating a problem.

The time of 3.5 minutes was selected as this means that 3 successive update messages have to be missed before a system alarm occurs. Also note, that if module #96 fails, DO4 will reset and give an alarm signal.